Factory default for the output relay is set to "During Run", the Multi-Function Output Selection Parameter n040 should be set to "0" in order to indicate the FAULT via relay output.

| MA | Multi-function contact output - NO contact | Factory | Contact capacity: |
|----|--|-----------|------------------------|
| MB | Multi-function contact output - NC contact | Setting | 250 Vac at 1A or below |
| MC | Multi-function contact output - Common | is 'Drive | 30 Vdc at 1A or below |
| | | Running' | |

Other settings for the Multi-Funtion Relay Output by the parameter n040.

| | Table 5-3. Mo | ulti-function Output Terminals | | |
|-----------------|--|--|--|--|
| Set Description | | | | |
| Value | Condition | Signal Level | | |
| 0 | Fault | Closed = Drive fault has occurred (except CPF0, CPF1) | | |
| 1 | During operation | Closed = Drive is operating | | |
| 2 | Speed at set frequency | Closed = Frequency Reference = output frequency See paragraph 5.18A | | |
| 3 | Zero Speed | Closed = Drive is at zero Hz. | | |
| 4 | Frequency detection - low | Closed = Output frequency ≤ n58. See paragraph 5.18B | | |
| 5 | Frequency detection - high | Closed = Output frequency ≥ n58. See paragraph 5.18C | | |
| 6 | Overtorque detection (N.O. contact) | Closed = Overtorque detected See paragraph 5.19 | | |
| 7 | Overtorque detection (N.C. contact) | Open = Overtorque detected See paragraph 5.19 | | |
| 10 | Alarm (minor fault) | Closed = Alarm condition is present | | |
| 11 | During coast to stop | Closed = Drive output base block is active; motor is coasting | | |
| 12 | Local/Remote Open = Frequency and Run Command by ext. input Closed = Frequency and Run Command by Digital (| | | |
| 13 | Operation ready | Closed = Drive is ready for operation (not faulted) | | |
| 14 | Auto-restart | Closed = During auto-restart operation | | |
| 15 | During Undervoltage | Closed = Drive has an undervoltage fault or warning | | |
| 16 | During Reverse run | Closed = Drive operation in reverse | | |
| 17 | During Speed Search | Closed = Drive performing a speed search | | |
| 18 | Serial communication | Closed = Command from serial communication | | |

Note: Earlier versions of the J7 Drive were named GPD 305/J7, GPD 305 or VS Mini J7.