Application Note

Adding an MPiec Controller as an EtherNet/IP Adapter to Allen Bradley ControlLogix 5555

Applicable Product: MPiec, ControlLogix 5555

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Title: Adding an MPiec as an EtherNet/IP Adapter to AllenBradley ControlLogix 5555		

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1. Application Overview

This application note illustrates how to add an MPiec motion controller as an EtherNet/IP Adapter (Generic EIP Device) to Allen Bradley's ControlLogix 5555 using RSLogix 5000 PLC application software and MotionWorksIEC. Additionally, a detailed description of how to create, link and verify communication via I/O variables is provided.

2. Application Requirements

The requirements for this application note include using the MPiec motion controller as an EIP Adapter (Slave) device to talk to and exchange data with an Allen Bradley ControlLogix PLC Scanner (Master). The example explained in this note describes an implicit I/O message connection between the MPiec and the AB PLC. No function blocks or PLC logic is necessary, since the data connection is open once the Assembly instances are correctly configured.

Components:

- MPiec Controller
- AB RSLogix5000© version 13.0
- AB ControLogix 5555 1756-L55 B Series PLC with CPU and Ethernet/IP Module (revision 13.27)

3. Application Solution and Benefits

- This configuration will allow the user to exchange data between the Allen Bradley ControlLogix 5555 PLC and the MPiec Motion Controller using EtherNet/IP as the protocol.
- Both Input and Output data tags are supported.

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4. System layout

Figure 1 details the goal of this project



Figure 1: System Layout

5. Configuring the Scanner (AB ControlLogix 5555)

This document explains configuration of the EtherNet/IP Module and the EtherNet/IP Assembly instances on both the MPiec device (Adapter) and the AB PLC device (Scanner).

In RSLogix 5000, start a new project. Enter the controller details as shown in Figure 2

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👫 RSLogix 5000		
File Edit View Search Logic Com	munications Tools Window Help	
		38 E 🛛
No Controller 🛛 🗸 🔲 RUN	□ Path: AB_DF1-1\1	
No Forces		-()(U)(L)-
Hedundancy vy	L P Pavorites Bit Timerico	unter 👗 input/outp
New Controller		×
Vendor:	Allen-Bradley	
Туре:	1756-L55 ControlLogix5555 Controller	OK
Revision:	13 💌	Cancel
	Redundancy Enabled	Help
Name:	AB_Master	
Description:		
Chassis Type:	1756-A7 7-Slot ControlLogix Chassis	
Slot	0 🗧	
Create In:	C:\RSLogix 5000\Projects	Browse

Figure 2: Starting a new project

The next step is to add the MPiec as a Generic EIP device by adding an Ethernet Bridge to the I/O Configuration. Right-Click on the I/O Configuration > Click 'New Module':





Figure 3: Adding an Ethernet bridge

Select the 1756 10/100 Mbps Ethernet Bridge, Twisted-Pair Media as shown in Figure 4.



Select Module Type × 1756-ENBT/A Type: Туре Description 1756-DMD30 1756 SD3000 Drive Interface 1756-DMF30 1756 SF3000 Drive Interface 1756-DNB 1756 DeviceNet Scanner 1756-ENBT/A 1756 10/100 Mbps Ethernet Bridge, Twisted-Pair Media 1756-ENET/A 1756 Ethernet Communication Interface 1756-ENET/B 1756 Ethernet Bridge 1756-EWEB/A 1756 10/100 Mbps Ethernet Bridge w/Enhanced Web Services 1756-HSC 1756 High Speed Counter 1756-HYD02 2 Axis Hydraulic Servo 1756-IA16 16 Point 79V-132V AC Input 1756-IA16L 16 Point 79V-132V AC Isolated Input 1756-IA8D 8 Point 79V-132V AC Diagnostic Input 1756-IB16 16 Point 10V-31.2V DC Input 1756-IB16D 16 Point 10V-30V DC Diagnostic Input • Show Vendor: All -Select All ☑ Other ☑ Specialty I/O 🗹 Analog 🔽 Digital 🔽 Communication 🔽 Motion 🔽 Controller Clear All ΟK Cancel Help

Figure 4: Selecting the Ethernet bridge type

Next, we configure the EtherNet/IP Module (Figure 5). Note: The IP address in this case is the IP address of the EtherNet/IP Module. Click on the '1756-ENBT/A *DeviceName*' node in the I/O Configuration section > Right-click the node and select 'Properties' to get the properties dialog (Figure 5)

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🎇 RSLogix 5000 - AB_Master [1756-L55]*	
File Edit View Search Logic Communications	Tools Window Help
	<u>. ≪⊗⊗</u> <u>∎</u> <u>2</u> 2
Offline Image: Constraint of the constraint	Path: AB_ETHIP-1\192.168.207.231\Backplane\0* Image: State of the state of
Controller AB_Master Controller Tags Controller Fault Handler Power-Up Handler Tasks MainTask MainTask MainProgram Unscheduled Programs Motion Groups Ungrouped Axes Trends Data Types Data Types Vuger-Defined Predefined Predefined J/O Configuration [1] 1756-ENBT/A EIP_Master	Module Properties - Local:1 (1756-ENBT/A 1.1) Type: 1756-ENBT/A 1756 10/100 Mbps Ethernet Bridge, Twisted-Pair Media Vendor: Allen-Bradley Parent: Local Name: EIP_Master Description: Image: Parent is the image is the imag

Figure 5: Setting general properties for the EtherNet/IP module on the Scanner

If you need to do any additional port configuration, click-on the 'Port Configuration' tab in the dialog window.

Next, the MPiec needs to be added as a Generic EIP device. Right Click on EIP Bridge node ([1] 1756-ENBT/A *'Device Name'*) under I/O Configuration > Click on 'New Module', and select the following from the 'Select Module Type' dialog:



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Select Module Type		×
Type: ETHERNET-MO	DULE	
Туре	Description	
1788-ENBT/A	1788 10/100 Mbps Ethernet Bridge, Twisted-Pair Media	<u> </u>
1788-EWEB/A	1788 10/100 Mbps Ethernet Bridge w/Enhanced Web Services	
1794-AENT/A	1794 10/100 Mbps Ethernet Adapter, Twisted-Pair Media	
Drivelogix5730 Ethernet	. 10/100 Mbps Ethernet Port on DriveLogix5730	
EtherNet/IP	SoftLogix5800 EtherNet/IP	
ETHERNET-MODULE	Generic Ethernet Module	
ETHERNET-PANELVIEW	Ethernet/IP Provide Sthewart Madula	
PowerFlex 700 Vector-21	. PowerFlex 7bo vector Drive (2007240V) via 20-COMM-E	
PowerFlex 700 Vector-4I	. PowerFlex 700 Vector Drive (400/480V) via 20-COMM-E	
PowerFlex 700 Vector-6I	. PowerFlex 700 Vector Drive (600V) via 20-COMM-E	
PowerFlex 700-200V-E PowerFlex 700 Drive (208/240V) via 20-COMM-E		
PowerFlex 700-400V-E PowerFlex 700 Drive (400/480V) via 20-COMM-E		
PowerFlex 700-600V E PowerFlex 700 Drive (600V) via 20 CDMM-E		
PowerFlex 700S-200V-E	PowerFlex 700S Drive (208/240V) via 20-COMM-E	-
- Show		
⊻endor: All	▼	
🔽 Analog 🔽 Digita	I 🔽 Communication 🔽 Motion 🔽 Controller Clear All	
	OK Cancel Help	

Figure 6: Selecting the adapter module type

Right Click on the newly created ETHERNER-MODULE and edit the properties as shown in Figure 7

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The following dialog should be displayed to configure the MPiec EIP Adapter:

🔀 R5Logix 5000 - AB_Master [1756-L55]*			
File Edit View Search Logic Communications	Tools Window Help		
	<u>. 68 8 8 F</u> 22		
	Path: AB_ETHIP-1\192.168.207.231\Backplane\0*		
No Edits	Image: Second		
Controller AB_Master Controller Tags Controller Fault Handler Power-Up Handler Tasks Tasks MainTask MainTask MainTask Motion Groups Unscheduled Programs Unscheduled Programs Unscheduled Programs Data Types Ungrouped Axes Trends Data Types User-Defined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Fredefined Configuration Configuration Fredefined Fredef	Module Properties - EIP_Master (ETHERNET-MODULE 1.1) Type: ETHERNET-MODULE Generic Ethernet Module Vendor: Allen-Bradley Parent: EIP_Master Name: Siec_EIPSlave Description: Assembly Input: 101 64 (16-bit) Output: 111 64 (16-bit) Output: 111 64 (16-bit) 0utput: 111 64 (16-bit) 9 111 64 (16-bit) 9 111 111 (8-bit) 9 111 111 (8-bit) 9 111 111 (8-bit) 9 111 111 (8-bit) <td< td=""></td<>		

Figure 7: Ethernet Module (adapter) properties

Notes about the Generic Ethernet Device Properties:

- 1. IP Address is the EIP Adapter.
- 2. Assembly Instances are referenced to the Master, meaning Input in this context is input to the Scanner (Master), output to the Adapter (Slave).

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Note: Special attention needs to be paid to the assembly instances and their sizes. If the sizes are not compatible, an error in communication will result. In this case sixty four sixteen bit registers make up the 128 bytes that instances 101 and 111 are made up of. This is compatible with the 128 eight bit registers on the MPiec side.

3. Configuration is not used on the MPiec controller. Therefore, this can be set to Assembly Instance #1, Size 1 since the assembly number can not be left blank.

Finally, configure the RPI (Requested Packet Interval) on the Master to dictate the polling rate to which the Master will update new packet information from the Slave. **The minimum value for the MPiec is 10ms.** Click on the 'Connection' tab in the Module Properties dialog

Module Properties - EIP_Master (ETHERNET-MODULE 1.1)
General Connection Module Info
<u>R</u> equested Packet Interval (RPI): 10.0 + ms (1.0 - 3200.0 ms)
Major Fault On Controller If Connection Fails While in Run Mode
-Module Fault
Status: Offline OK Cancel Apply Help
Figure 8: RPI properties

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Verify the created project by clicking on the verify button as shown in Figure 9.

Tools Window Help		
- B BB []		Q
Path: AB_ETHIP-1\192.168.207.231\Backplane\0	×	- ₩
H H	out 🔏	▶ Compare
Controller Tags - AB_Master(controller)		
Scope: AB_Master(controller Show: Show Al		▼ S
Tag Name 🛆 Value 🗲 Force	Mask	🗧 🗲 Style

Figure 9: Verify

Download the project to the controller by verifying the path to download. Communications > Who Active

👫 RSLogix 5000 - AB_Master	[175	6-L55]*			
File Edit View Search Logic	Con	munications	Tools	Win	dow Help
	몲	<u>W</u> ho Active			
		<u>S</u> elect Recen	t Path.		
Offline 🛛 🗸 🗖 RUN				-	h: AB_ETHIP
No Forces		<u>G</u> o Online			
No Edits 🔒 🗖 No Edits		Upload			
Redundancy		<u>D</u> ownload			avorites 🖌 Bit

Figure 10: Verify path for download

Select the controller to which this project is going to be downloaded and click download as in Figure 11.





Figure 11: Download to ControlLogix

Once downloaded, go online.

At this point, the scanner device (AB PLC) is configured to talk with the MPiec as an adapter. Additionally, the RSLogix 5000 software automatically adds the words configured for the EIP module. These can be located in the 'Controller Tags' node under the 'Controller' node in the project tree:

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Figure 12: Controller tags for I/O variables

6. Configuring the Adapter (MPiec)

The next steps illustrate how to create a project in MotionWorks IEC and add I/O variables to talk with the AB PLC.

Since Assembly Instances #101 (Scanner Inputs) and #111 (Scanner Outputs) were configured on the scanner device, the next task is to implement the data exchange between the scanner and the adapter. To do this, we need to add I/O variables using the pre-defined address ranges as specified in the MPiec Project Template. This is the template that opens when a user chooses to open a new project in MotionWorksIEC as shown in Figure 13.

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Figure 13: New project in MotionWorksIEC

After the new Project is created, select the 'Global_Variables' tab in the Project Tree

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Name Туре Usage. Description Address System EAP Input Instance #111, Qty: 128 Bytes, Address Range: %IB0-%IB127 FromControl1 INT VAR GLOBAL %M/0 EAP Input Instance #112, Qty: 256 Bytes, Address Range: %IB128 - %IB383 E/IP Input Instance #113, Qty: 128 Bytes, Address Range: %IB384 - %IB511 EIP Input Instance #114, Qty: 256 Bytes, Address Range: %IB512 - %QI767 🖃 EAP Input Instance #115, Qty: 128 Bytes, Address Range: %IB768 - %IB895 🖃 EAP Input Instance #116, Qty: 256 Bytes, Address Range: %IB896 - %IB1151 E/IP Output Instance #101, Qty: 128 Bytes, Address Range: %QB0 - %QB127 VAR GLOBAL %QW0 ToControl1 INT. E/IP Output Instance #102, Qty: 256 Bytes, Address Range: %QB128 - %QB383 E/IP Output Instance #103, Qty: 128 Bytes, Address Range: %QB384 - %QB511 E/IP Output Instance #104, Qty: 256 Bytes, Address Range: %QB512 - %QB767 E/IP Output Instance #105, Qty: 128 Bytes, Address Range: %QB768 - %QB895 E/P Output Instance #106, Qty: 256 Bytes, Address Range: %QB896 - %QB1151 🖃 Modbus FC#02 Qty: 128 Inputs, Address Range: %QX1152.0 - %QX1167.7 □ Modbus FC#04 Qty: 1024 Registers, Address Range: %QB1168 - %QB3215 □ Modbus FC#05 Qty: 128 Coils, Address Range: %IX1152.0 - %IX1167.7 🖃 Modbus FC#06,16 Qty: 1024 Registers, Address Range: %IB1168 - %IB3215 Ello-01> - Module - 1 (* Modify Variable Names, Not Group Name!! *)

Figure 14: Global Variable list

Start adding I/O variables to the Global Variables table. In this example, we will adding (1) input WORD (16bit) variable and (1) output WORD variable. A new variable can be created by right clicking on the grey input or output instance group name and choosing so.

Next, we assign each variable an address based on the variable group description range. Note: Addressing in the MotionWorks IEC project is based on byte offset; i.e. %QW0 = Word 0, %QW1 = Word 1, etc.

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The exercise carried out in this test project is as follows



Figure 15: Test exercise

Create the following logic on the slave MPiec controller. Download the program and run the controller.



Figure 16: Logic on the MPiec

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7. Communication Verification

After both devices and variables are configured, each program can be run and tested using the debuggers on both the Master and Slave devices.

Enter an integer in the scanner output variable



Figure 17: Scanner output variable

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The corresponding scanner input variable will have the value of the scanner output variable incremented by one. This addition took place in the MPiec controller.



Figure 18: Scanner input variable

To verify the AB PLC has connected correctly to the MPiec controller and the configured Assembly Instances are functioning properly, there is a dialog in RSLogix that displays the status as shown in Figure 19.

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Module Proper	ties - ENBT (ETHERNET-MODULE 1.1)
General Connec	tion Module Info
<u>R</u> equested Pack	et Interval (RPI): 100.0 ms (1.0 - 3200.0 ms)
Major Fault O	In Controller If Connection Fails While in Run Mode
- Module Fault-	
	Status Messages Displayed Here
Status: Offline	OK Cancel Apply Help

Figure 19: Communication status display