MOTIONPACK-SG1 SINGLE AXIS MOTION CONTROLLER PROGRAMMER DESCRIPTIVE INFORMATION





Safety Precautions

Safety precautions in this manual apply to MOTIONPACK-SG1.

Please read this manual carefully and be sure you understand the information provided before operation.

Keep this manual at your disposal for daily maintenance and inspection.

General Precautions

- Some drawings in this manual are shown with the protective covers or shields removed, in order to describe the detail with more clarity. Make sure all covers and shields are replaced before operating this product, and operate it in accordance with the directions in the manual.
- The figures and photographs in this manual show a representative product for reference purpose and may differ from the product actually delivered to you.
- This manual may be modified when necessary because of improvement of the product, modification, or changes in specifications.
 Such modification is made as a revision by renewing the manual No. on front cover.
- To order a copy of this manual, if your copy has been damaged or lost, contact
 your Yaskawa representative listed on the last page starting the manual No. On the
 front page.
- If any of the nameplates affixed to the product become damaged or illegible, please send the nameplates to your Yaskawa representative.
- Yaskawa is not responsible for any modification of the product made by the user since that will void our guarantee.

Notes for Safe Operation

Read this manual thoroughly before installation, operation, maintenance or inspection for the MOTIONPACK-SG1.

The functions and performance are not determined only by positioning control device itself. Before operation, read thoroughly the machine tool builder's documents relating to the machine tool concerned.

In this manual, the Notes for Safe Operation are classified as "WARNING" or "CAUTION".



: Indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury to personnel.

Symbol is used in labels attached to the product.



: Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury to personnel and damage to equipment.

It may also be used to alert against unsafe practices.

Even items described in A CAUTION may result in a vital accident in some situations. In either case, follow these important items. Please note that symbol mark used to indicate caution differs between ISO and JIS.

ISO	ЛЅ
<u> </u>	! >

In this manual, symbol mark stipulated by ISO is used.

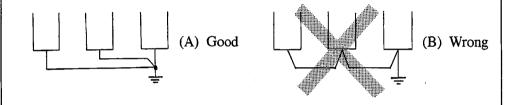
On products, caution symbol marks of ISO and JIS are used in labels.

Please follow the same safety instructions concerning caution.

1 APPLICATION SAFETY PRECAUTIONS

! WARNING

- Make sure to note the following precautions in order to avoid any risk of electric shock or machine malfunctions.
 - Do not touch any unit, terminals, etc. while the power is ON.
 Failure to observe this warning may lead to electric shock or device malfunction.
 - Immediately after switching the power OFF, the product retains some electric charge. Do not touch any parts which are live when the power is ON for 5 minutes after switching the power OFF.
 Failure to observe this warning may lead to electric shock or device malfunction.
 - Select the cable size in conformance with local electrical codes or the cable manufacturer's technical data.
 - Ground at one point. (Ground resistance 100 Ω or less)
 - Be sure to separate the grounding line of the unit from a power unit. Failure to observe this warning may lead to malfunction.
 - When more than one unit exists, grounding should be made as shown in Fig. (A), but not as shown in Fig. (B).



- Do not damage cables, subject them to excessive stress, or pinch them. Excessive load on cables may cause electric shock.
- When the unit is turned ON, never touch its rotating parts.
 Failure to observe this warning may result in personal injury.
- Never modify the product.
 Failure to observe this warning may result in electric shock, fire, or product failure.

1 APPLICATION SAFETY PRECAUTIONS (Cont'd)

! CAUTION

- Use the product in an environment with the following characteristics.
 Using it in an environment in which it is subject to high temperatures, high humidity, dust, corrosive gasses, vibration or impacts may cause fire, electric shock or malfunction.
 - ① Free from gasses or vapors that create a potentially explosive atmosphere.
 - ② Free from corrosive oil, organic solvents, etc.
 - 3 Relative humidity in the range 30 to 85 % RH, with no condensation.
 - ④ Ambient temperature in the range 0 to 55 °C with no freezing.
 (Installation site must not be exposed to direct sunlight, must be distanced from heat generating devices, and must be indoors.)
 - (0.5 G) Sibration not exceeding 4.9 mm/s² (0.5 G).
- Install the units in accordance with the following.
 Failure to observe this caution may result in product failure or malfunction.
 - ① Mount the unit vertically with screws or bolts.
 - 2 The unit will generate heat, therefore, install it with adequate clearance around it.
 - ③ When circulating air inside the enclosure, do not blow air directly onto the unit (in order to prevent dust contamination).
 - Arrange units so that maintenance, inspection or replacement of parts may be made easily.
- Design and install the box in accordance with the following.
 Failure in box such as electric control panel may result in product failure or malfunction.
 - ① Use an airtight enclosure.
 - 2 Limit the average temperature increase of internal air within the enclosure to under 10 °C (50 °F) compared to the ambient temperature.
 - 3 Use a fan to circulate air in order to improve the cooling efficiency of a closed enclosure and to prevent abnormal temperature rise.
 - 4 Seal the cable inlet, door, etc. completely.
 - The board inside the unit attracts airborne particles because of its high voltage and may result in malfunction, therefore, provide a structure to prevent the entry of dust.
 - 6 Install packing on the cable inlet, doors, back covers, etc. to eliminate gaps or openings.
- Do not let foreign matter such as electric wire scrap enter the unit.
 Failure to observe this caution may result in fire, product failure or malfunction.
- Set the power line capacity higher than the power consumption of the device. Failure to observe this caution may result in product malfunctions.
- The current capacity of 24 VAC external power unit for input/output contacts is determined by the number of contact points to be used. When the current capacity is low, install an additional external power unit.

2 RECEIVING

⚠ CAUTION

Check the product if it meets your order.
 Installation of improper product may result in personal injury or product damage.

3 STORAGE

⚠ CAUTION

 Do not store the product in locations subject to rain, water droplets, or harmful gases or liquids.

Failure to observe this caution may result in product failure.

 Select a storage area indoors that is clean and meets the following temperature and humidity requirements.

Failure to observe this caution may result in product failure.

Ambient temperature: -20 °C to +85 °C

Relative humidity: 10 % to 90 %

4 TRANSPORT

⚠ CAUTION

• Do not lift the cable when moving the product.

Failure to observe this caution may lead to personal injury or product failure.

5 INSTALLATION

- When installing the product, avoid shutting the inlet port or exhaust port.
 Also avoid foreign matter from entering the device.
 Failure to observe this caution may lead to fire or product failure.
- Avoid strong impact during installation.
 Failure to observe this caution may result in product failure.

! CAUTION

Always turn the power OFF (including the primary power supply) before carrying out the wiring.

Carrying out the wiring with the power ON may lead to electric shock.

Be sure to connect the grounding terminal of the motor to the grounding terminal of the drive unit.

Failure to observe this caution may lead to electric shock, fire, or malfunction.

- Ground at one point (Ground resistance 100 Ω or less) Failure to observe this caution may lead to electric shock, fire, or malfunction.
- Be sure to separate the grounding line of the unit from a power unit. Failure to observe this warning may lead to malfunction.
 - Correct and precise wiring should be performed by qualified, authorized personnel only.

Failure to observe this caution may result in electric shock, fire, or malfunction.

 Select the type of wire and its size according to your requirement and current capacity.

When the ambient temperature exceeds 30 °C(86°F), the allowable current goes down.

 Select the cable size in conformance with local electrical codes or the cable manufacturer's technical data.

Failure to observe this caution may result in fire.

- Use twisted wire or multi-core twisted pair shielded wire for general signal wires and feedback signal wires for the encoder.
 This helps the prevention of malfunction.
- Connect wires in the shortest possible length.

 This helps the prevention of malfunction.
- Connect the power supply of 100/110 VAC to the control power terminal.
 Connect the power supply of 24 VDC to the terminal of I/O signals.
 Connecting it to power supply with different voltage may cause fire.
 - ① The input power supply to CPU unit works normally until a momentary power loss of 1/2 cycle or the voltage drop by 50% within 1 cycle.
 - ② The allowable range of voltage fluctuation should be -15% to 10%; however, use the average voltage at the rated 200 VAC, 220 VAC, or 230 VAC.
- External connection wiring should be made with consideration of the following points:

Failure to observe this caution may result in fire or malfunctions.

- · Mechanical strength
- · Influence of noise
- · Wiring distance
- Signal voltage

⚠ CAUTION

- Do not run the I/O signal wires with power wires or in the same duct with power wires.
 - Sufficient separation of signal wires from power wires will reduce the noise influence slight.
- In the event of noise from a power wire, use a noise filter to prevent it.

 Correct use of noise filter will reduce the noise influence.

7 OPERATIONS

- Before carrying out cutting operation with a new program, confirm safety by performing single block operation.
 - If this check operation is not performed, unexpected operation may be performed due to mis-setting of the amount of offset, and resulting accidents involving injuries to personnel.
- The end user must not change parameters relating to machine accuracy, travel axis control and spindle axis control.
 - The parameters are set to the optimum values for each machine, and changing them could therefore result in unexpected operation. This could cause tool damage due to interference, and resulting accidents involving injuries to personnel.
- Strictly observe the cautions in the user's manual when using programming functions.
 - Ignoring these cautions could lead to accidents involving injuries to personnel and malfunctions.

8 MAINTENANCE AND INSPECTION

/!\ WARNING

- Always turn the power OFF (including the primary power supply) before carrying out daily inspection.
 - Carrying out the inspection with the power ON may lead to electric shock.
- Wait 5 minutes after turning the power (including the primary power supply)
 OFF before removing or replacing any unit or part.
- Be sure to turn the power OFF before replacing the battery. Failure to observe this warning may lead to electric shock.

⚠ CAUTION

• To prevent personnel other than those involved in maintenance and inspection work from turning the power ON while maintenance and inspection is in progress, place sign stating "Do not turn the power ON" or words to that effect at the primary power supplies of related control panels and other relevant locations.

Failure to observe this caution may lead to electric shock.

- Replace fuses and batteries with the designated products.
 Failure to observe this caution may result in fire or product failure.
- Electric devices such as CMOS ICs are used on the control boards. If you touch them with your bare fingers the static electrical charge in your body could destroy them; care must be taken when handling these devices. Before handling these devices for maintenance purposes, first discharge the statistic electricity in your body by touching a grounded metal device. Failure to observe this caution could lead to injuries and product failures.
- Do not install or remove boards, wiring, connectors, etc., while the power is ON.

Failure to observe this caution could lead to electric shock, product failure, and malfunction.

When an alarm occurs, eliminates its cause and confirm safety before resetting it.

Failure to observe this caution could result in malfunction.

- Be sure to check the following points on completing maintenance and inspection work.
 - · Check that all fastening bolts are tightened.
 - Check that no tools or other objects have been left inside the control panel.
 - · Check that the control panel door is closed properly.

Failure to carry out these checks may lead to electric shock, injuries, fire, and malfunction.

- For details on trouble relating to the machine-related sequence, refer to the manual issued by the machine tool builder.
- Never attempt to disassemble or modify units or devices inside the control panel.

Failure to observe this caution may lead to fire, product failure, or malfunction.

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1 SPECIFICATIONS

Table 1.1 Specifications

item	Ratings					
Туре	JEMP-PSG1					
Indicator	Liquid crystal module with EL back-light 16 characters × 4 lines and display LEDs					
EL Service Lifetime	Luminance is deteriorated a little after approx 2000 hours elapse.					
Switch	Operation key switch × 40					
Auxiliary Memory Unit	No-contact method memory card (reader/writer built-in)					
Printer Board	RS-232C level interface built-in (D-SUB 9-pin)					
Power Supply	Supplied from controller through cable					
Environment	Operation ambient temperature: 0 to 50°C natural air cooling Storage ambient temperature: -20 to +60°C Ambient humidity: 30 to 95%RH (non-condensing) Vibration resistance: In accordance with JIS C 0911 (up to 1G) Shock resistance: In accordance with JIS C 0912 (up to 10G) Atmosphere: Free from inflammables, corrosive gases, dust, metallic dust, high temperature or high humidity.					
External Dimensions	85 (W) × 190 (H) × 37 (D) (in mm)					
Approx. Mass	450 g					

2 PANEL

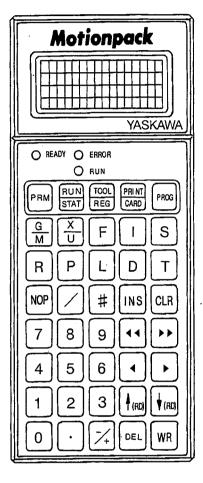


Fig. 2.1 Panel

Key Name	Functions (Applications)				
PRM	Used for parameter checking or setting.				
REG	Used for register checking or setting.				
TOOL	Used for compensated value checking or setting.				
PROG	Used for program checking, change, creation, deletion or move.				
RUN	Used for current operation status checking.				
STAT	Used for status checking.				
PRINT	Used for parameter, program, register or compensated value print-out.				
CARD	Used for parameter, program, register or compensated value load/save or checking card directory information.				
*	Used for data value change and moves the cursor to the head of the next (former) character line. (The cursor move is a rotation move.)				
*	Used for data value change and moves the cursor to the next character in a character line. (The cursor move is a rotation move.)				
DEL	Used for character deletion. (Characters after the deleted character go to one space to the left Used for program (block) deletion.				
CLR	When this key is pressed one time during any data setting in a menu that is currently developed, the screen before the data input is displayed. When it is pressed again, the latest input screen is displayed if there is a formally input menu selection screen; if not, the RUN status is displayed.				
NOP	Used for programming or NOP block creation.				
INS	Used for character insertion or block insertion.				
WR	Used for data writing-in to Motionpack SG1. Used for menu definition.				
↓ (↑)	Used for data read-in from Motionpack SG1. Used for page feeding.				
#	Used to express in hexadecimal (A to F) for parameter (SERVO, SPINDLE) check and setting. By selecting 0 to 5 after # is pressed, the value will be expressed in A to F respectively.				

Other keys are over-writing input (characters). / key is not used.

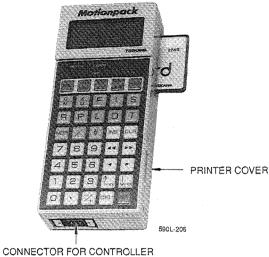
3 OPERATION METHOD AND CONNECTION

3.1 OPERATION METHOD

(1) Cable Connection

Connectors, one for connection with the controller and another for connection with the printer are provided for the programmer bottom and side, respectively.

Connect the programmer with the controller using exclusive-use cables. Do not fail to lock the connectors when the exclusive-use programmer is used.



(2) Operation

Fig. 3.1 Programmer

Since the programmer has the power supply and signals stored in a cable, it can operate as soon as the cable is connected. (See Table 3.1.)

The programmer does not have a reset key. If it is necessary to reset, remove the connector for controller and connect it again. (Reset is enabled at the power supply startup.)

Table 3.1 Contents of Display (Normal/Error)

Display	Color	Contents
READY	Green	Lights when exclusive-use programmer operates normally.
ERROR	Red	Lights when communication with controller is not executed normally.

(3) Panel Mounting

The programmer can be mounted on the panel face. In this case, mount the programmer at the rear side using three taps on the rear side.

(4) Liquid Crystal Adjustment

The programmer can adjust the liquid crystal display contrast or EL back-light luminance (bright) if necessary. For adjustment, open the printer cover and use a driver.

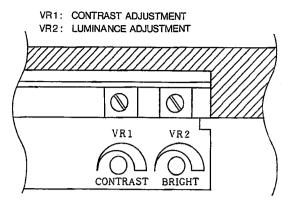


Fig. 3.2 Liquid Crystal Adjustment

(5) Precautions on Memory Card Application

Since the memory card is of no-contact method, it does not have any connectors.

Therefore, if the card is not inserted to the reader/writer slit firmly, the data cannot be read or written and "card access error" occurs. The error message is shown below.

The error also occurs if the card is removed during reading or writing since files in the card are damaged.

If "card access error" is displayed, insert the card again and attempt to execute. However, should the error not be cleared, it is necessary to execute the card all-clear.

C	а	r	d		а	С	С	е	s	s					
									е	r	r	0	r		
									<u></u> .						
	-	ก	п	S	h		C	I.	R		k	e	v	<u>:</u> —	:

3.2 CONNECTION WITH CONTROLLER

(1) Connector at Programmer Side

Main Port (DELC-J9PAF-12L9): Connection with controller

5		L	
		9	0 s V
4	*RXD		0.17
3	RXD	8	0 s V
		7	+5 V
2	*TXD	6	+5 V
1	TXD	1 0	+υ ν
1	IAD	ľ	

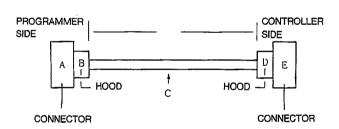
Connector No.	Programmer Side Connector	Applicable Connector	Hood	Manufacturer
Main	DELC-J9PAF-12L9	DE-9SF-N	DE-C8-J9-F1-1	JAE

(2) Connector at Controller Side

CN5 (DELC-J9SAF-12L9): Connection with programmer

,		5	
9	0 s V	-	*RXD
8	05V	4	
7		3	RXD
'	+5 V	2	*TXD
6	6 +5 V		TXD
			עאז

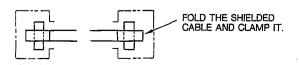
(3) Exclusive-use Cable (Attached)



Type: CMPR-WU13 (3 m)

Fig. 3.3 Exclusive-use Cable (Attached)

İ	A		C	I	E		
Connector		Cable U	L Shielded	Connector			
DE	-9SF-N	_Cable :	DP8409123	DE-9	PF-N_		
	Pin No.	Cable	Cable Color	Pin No.	Signal		
		Core			Name		
	1	Twisted	Grey	1	TXD		
	2	1 wisteu	White (grey)	2	*TXD		
	3		Orange	3	RXD		
	4	Twisted	White (orange)	4	*RXD		
	5		Light green	5			
	6	Twisted	White (light green)	6	+5 V		
	7		Red	7	+5 V		
	8		Yellow	8	GND		
	9		Green (yellow)	9	GND		



3.3 CONNECTION WITH PRINTER

Connection with the printer is in accordance with the RS-232C serial interface specifications. Hand-shake between the programmer and the printer is performed either by flag control method or X-ON/X-OFF control method.

(1) Flag Control Method

When the printer is in receiving disable status (e.g. when the buffer RAM memory is almost full), the output signal from the printer is turned off and transmission from the programmer is stopped temporarily. Then when transmission is ready, the printer turns on the output signal and the data transmission from the programmer is permitted.

This method is as shown in the Fig. 3.4.

TxD: Transmission data Receiving data RxD:

This signal status determined whether CTS:

a signal is output from TxD or not. Indicates the printer status, equivalent to "BUSY". REV.

Informs whether the printer can receive the data or not. DTR

Signal grounding SG:

Frame grounding

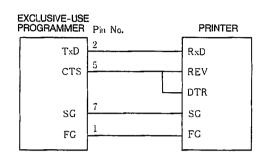


Fig. 3.4 Connection in Flag Control

(2) X-ON/X-OFF Control Method

The printer receiving status (whether it can receive the data or not) is controlled by sending a control code from the printer side.

X-ON (DC1 code <11H>) or X-OFF (DC3 code <13H>) is sent to the exclusive-use programmer when the printer is ready to receive the data or when the printer is not ready to receive the data, respectively, the exclusive-use programmer sends the data according to the instruction.

This method is as shown in the Fig. 3.5.

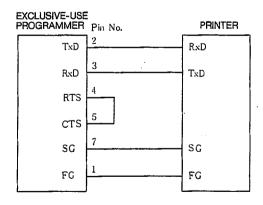


Fig. 3.5 X-ON/X-OFF Control Method

3.3 CONNECTION WITH PRINTER (Cont'd)

(3) Connector at Programmer Side

RS-232C port (DELC-J9SAF-12L9): Connection with printer

1	FG		T
	WAD	6	(RESERVED)
2	TXD	7	05V
3	RXD	<u> </u>	
1	RTS	8	(RESERVED)
4	N19	9	(RESERVED)
5	5 CTS		

Connector No.	Programmer Side Connector	Applicable Connector	Hood	Manufacturer
Printer	DELC-J9SAF-12L9	DE-9PF-N	DE-C8-J9-F1-1	JAE

4 FUNCTION LIST

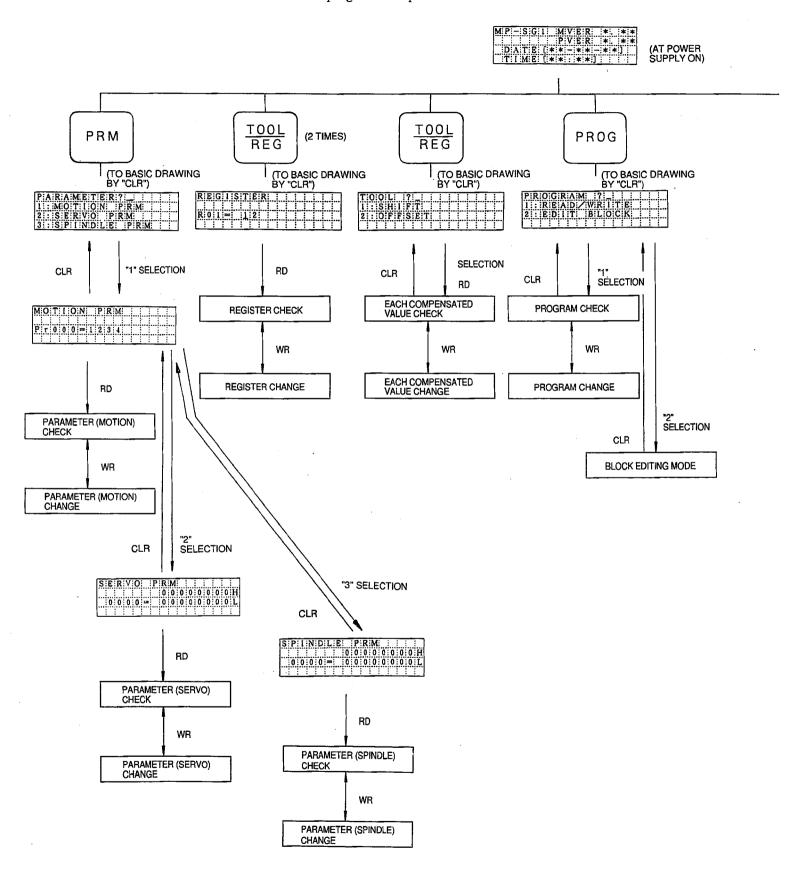
Table 4.1 Function List

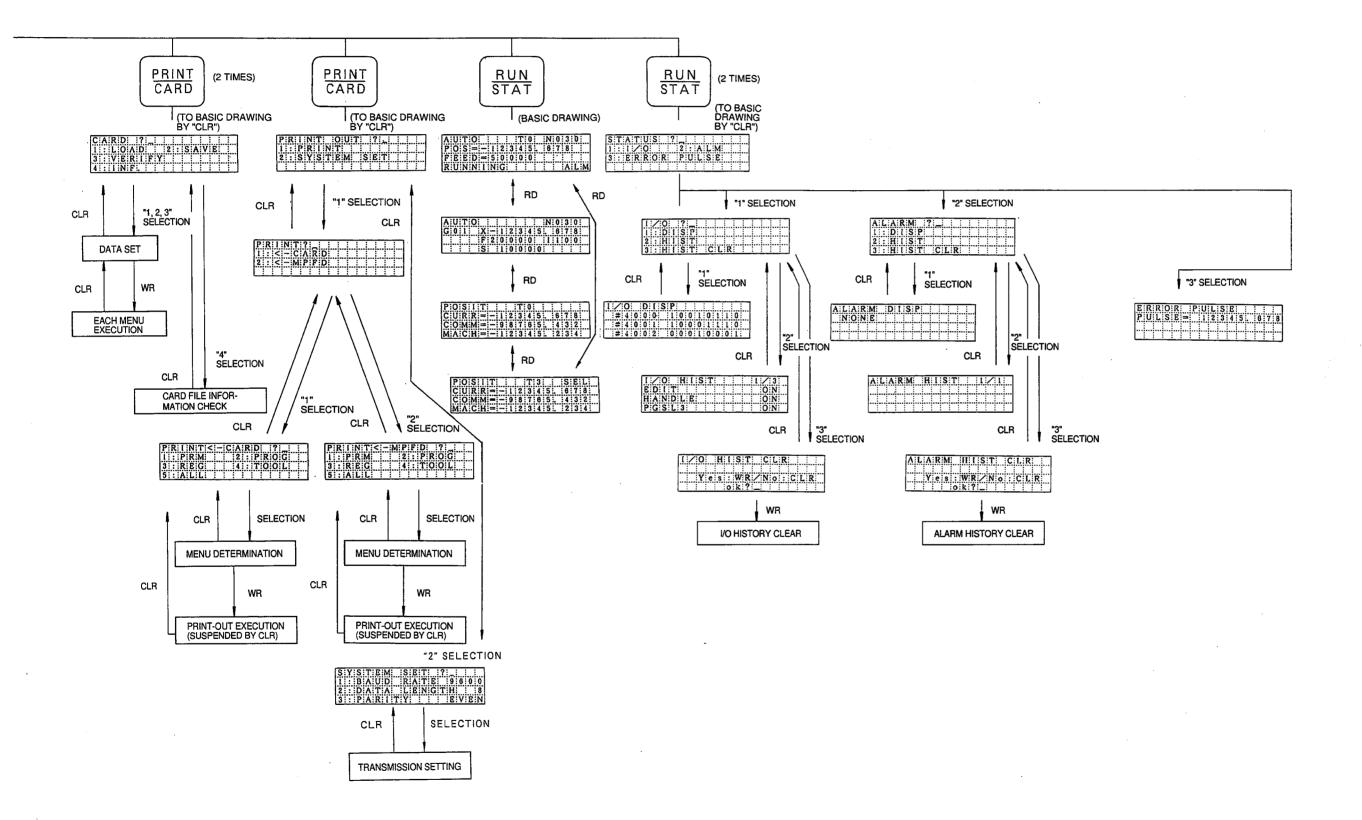
No.	Function Name	Contents
1	Parameter (MOTION) check	Displays the specified parameter (MOTION) contents.
2	Parameter (MOTION) set	Sets a value to the specified parameter (MOTION).
3	Parameter (SERVO) check	Displays the specified parameter (SERVO) contents.
4	Parameter (SERVO) set	Sets a value to the specified parameter (SERVO).
5	Parameter (SPINDLE) check	Displays the specified parameter (SPINDLE) contents.
6	Parameter (SPINDLE) set	Sets a value to the specified parameter (SPINDLE).
7	Register check	Displays the specified register contents.
8	Register set	Sets a value to the specified parameter.
9	Compensated value check	Sets a shifted value or offset value of the specified coordinate system.
10	Compensated value set	Sets a shifted value or offset value of the specified coordinate system.
11_	Program check	Displays the specified block program contents.
12	Program change	Sets a program to the specified block.
13	Program (block) deletion	Deletes the specified block program.
14	Program (block) copy	Copies the specified block program to other block.
15	Program (block) move	Moves the specified block program to other block.
16	Memory card read	Transmits a program or parameter from the memory card to the Motionpack.
17	Memory card write-verify	Transfer or verify a program or parameter from the memory card to the Motionpack.
18	Printer output	Outputs a program or parameter from the card to the printer.
19	RUN display (mode, current position, current N number, speed, waiting status, alarm occurrence)	Displays each data as described in the parentheses to the left in order to monitor the Motionpack run status.
20	RUN display (Current executing) program display	Displays the program contens that is being executed.
21	RUN display (Various position data)	Displays the position data in order to monitor the Motionpack run status.
22	Status display (I/O status)	Displays the I/O signal status in order to monitor the Motionpack run status.
23	Status display (alarm message display)	Displays an alarm message.
24	Status display (Position deviation) display	Displays the position deviation value.

5 OPERATION METHOD

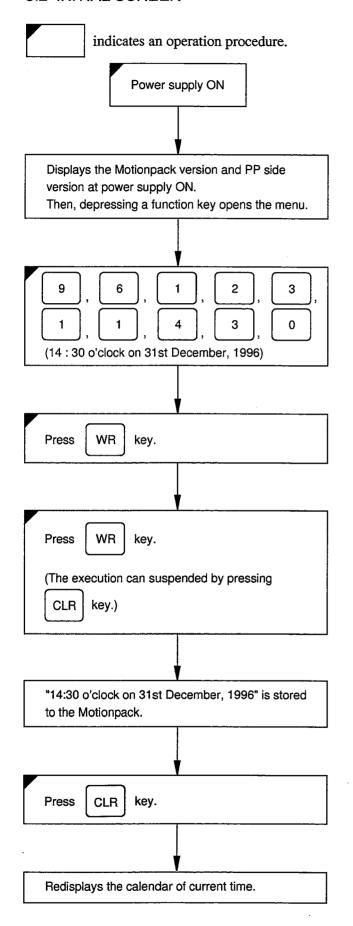
5.1 MENU FLOW CHART

The menu flow chart of the programmer operation is shown below.



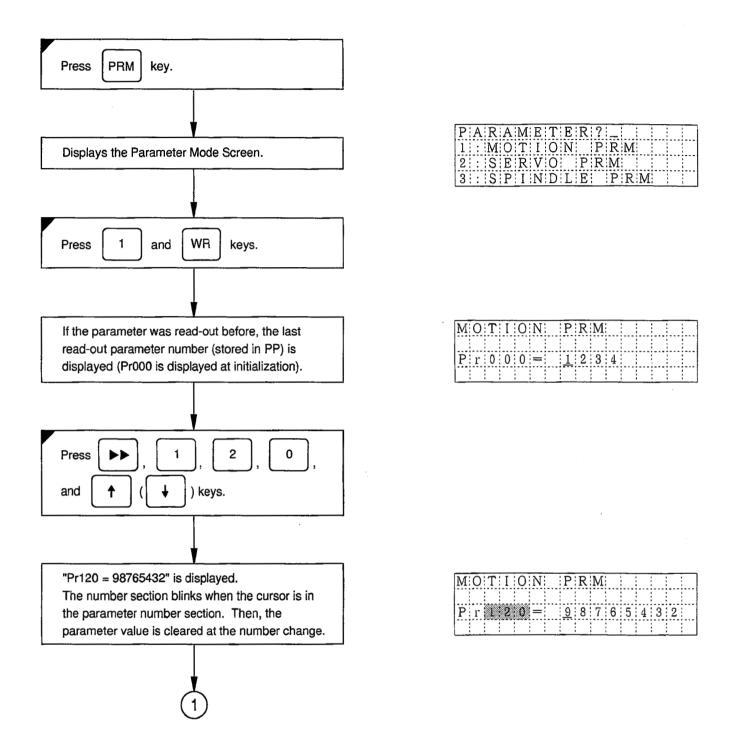


5.2 INITIAL SCREEN

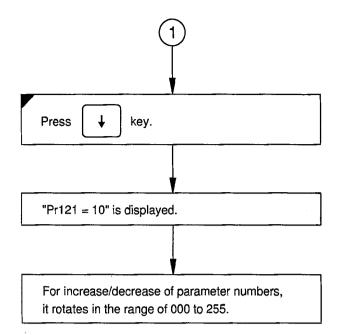


M:P-S:G:1 M:V:E:R * P:V:E:R * D:A:T:E:[**-**-* T:I:M:E:[**:**:]	* * * * * * * * * * *]
M: P - S G 1 M: V E R > P V E R > T I M: E [9 6 - 1 2 - 3 T I M: E [1 4 : 3 0]	*: * * *: * * 3 1]
D:A:T:E:/:T:I:M:E:	3 1]
D A T E / T I M E e n d	1)

5.3 PARAMETER (MOTION) CHECK

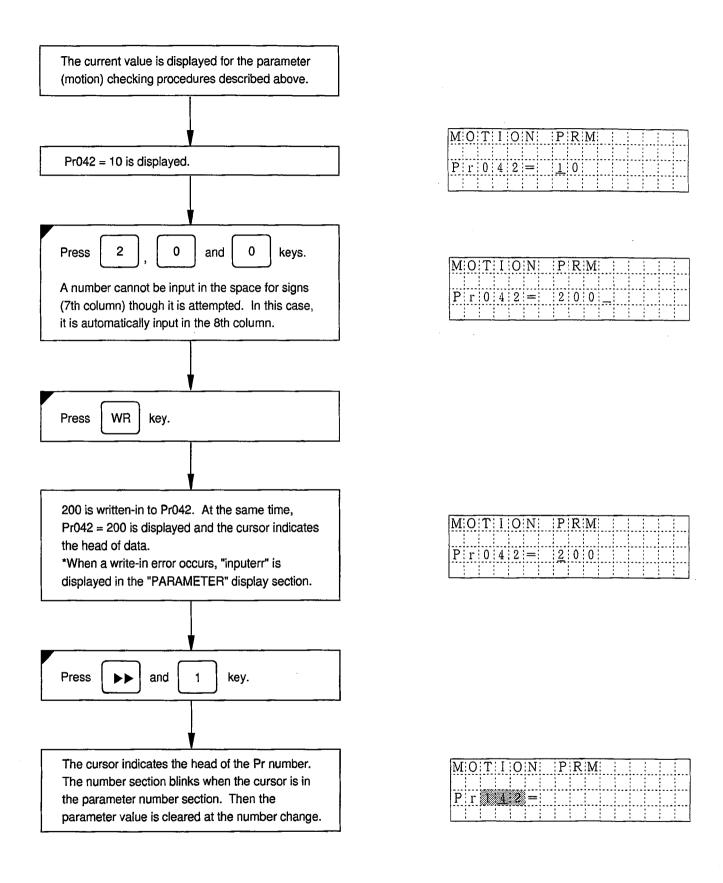


5.3 PARAMETER (MOTION) CHECK (Cont'd)

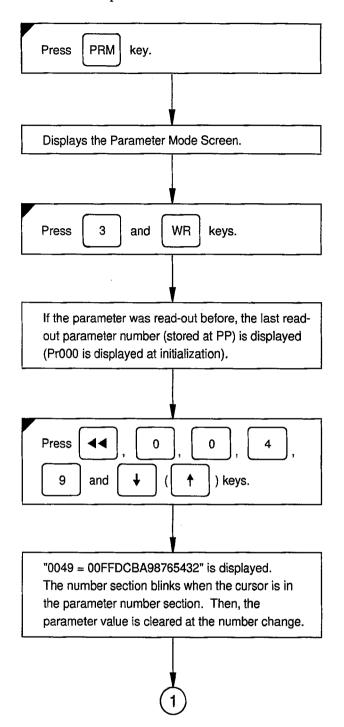


M	0 '	T	I	0	N	Р	R	М				
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										;	:	

5.4 PARAMETER (MOTION) CHANGE

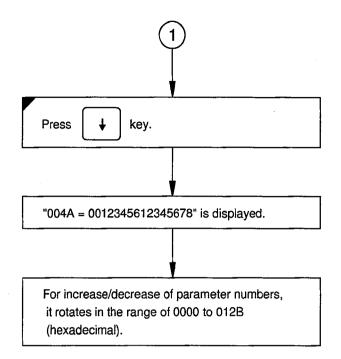


5.5 PARAMETER (SERVO) CHECK



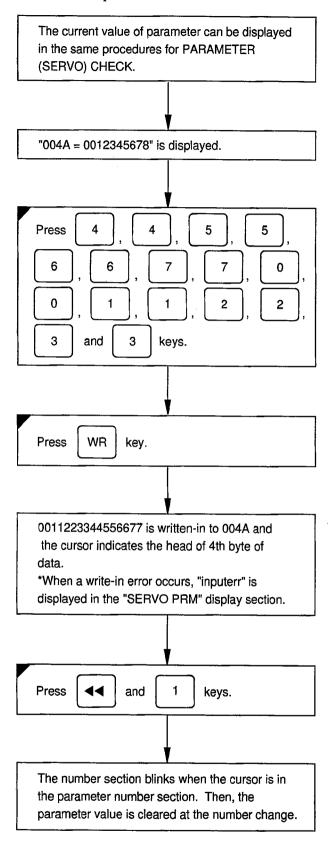
DIA DIA MEDINENINA
R A R A M E T E R ?
S:E:R:V:O: :P:R:M: : : : : : : : : : : : : : : : : :
0 0 A B C D E F H 0 0 0 0 0 = 1 2 3 4 5 6 7 8 L

SEI	R V O	Р	R M			
			0:0	FE	D C	B A H
0.1	0:4:9	=: :	<u>9</u> :8	7:6	5:4	3:2:L
1 :	: 1					: : :



S	E	R	V	0		Р		R	M							
								0	0	1	2	3	4	5	6	Н
	0	0	4	A	=			1	2	3	4	5	6	7	8	L
					:	:	;									

5.6 PARAMETER (SERVO) CHANGE



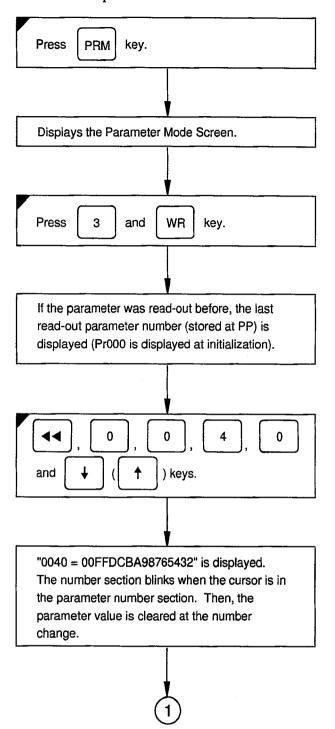
S	Ε	R	V	0		P	R	M	:		1				;
							0	0	1	2	3	4	5	6	Н
	0	0	4	Α	=	:	1	2	; 3	: 4	5	6	7	8	L
								:							

SE	R	V	0		Р	R	Μ							
						0	0	1	1	2	2	3	3	Η
0	0	4	Α	=		4	4	5	5	6	6	7	7	L

SE	R:V	7:0	P	R	M						:	
				0 :	0	1	1	2	2	3	3 :	Η
: 0	0:4	A	=;	4	4	5	5	6	6	7	7	L

SE	R:V	0:	P	R	M				
									Η
	<u>0</u> :4	A	=						L
					:				

5.7 PARAMETER (SPINDLE) CHECK

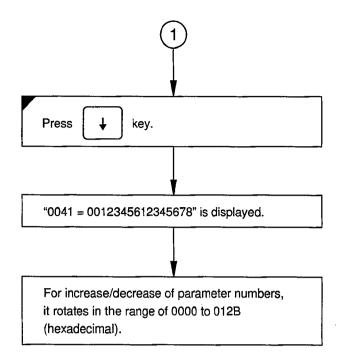


PARAMETER?	:
1 :: M:O:T:I:O:N: P:R:M	:
2 : SERVO PRM	
3 : S P I N D L E P R M	

SP	IN	1:D	LE	}}	P	R	M					
				0	0	Α	В	C	D	Ε	F	Η
0	0 (0 (=	1	2	3	4	5	6	7	8	L

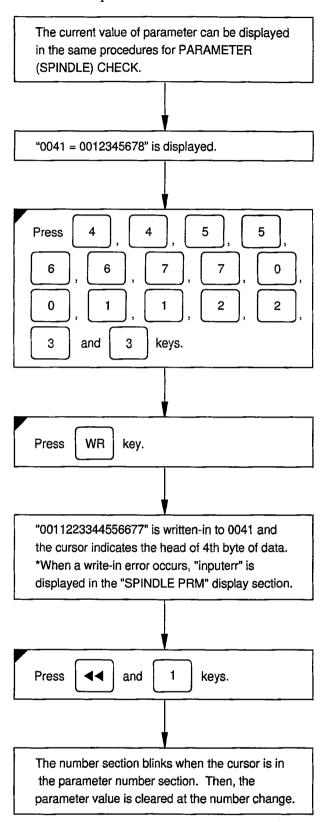
Ī	S	P	Ι	Ν	D	L	Ε		F	? R	M			:		
1				:				0	0	F	E	D	С	В	Α	Н
1		0	0	4	0	=		9	8	7	6	5	4	3	2	L
1		-	:	:				-	-					: · · ·		

5.7 PARAMETER (SPINDLE) CHECK (Cont'd)



SPI	N.D.L.E	PRM		
		0 0 1 2	3:4:5	6 H
0:0:	4 1 =	1 2 3 4	5:6:7	8:L

5.8 PARAMETER (SPINDLE) CHANGE



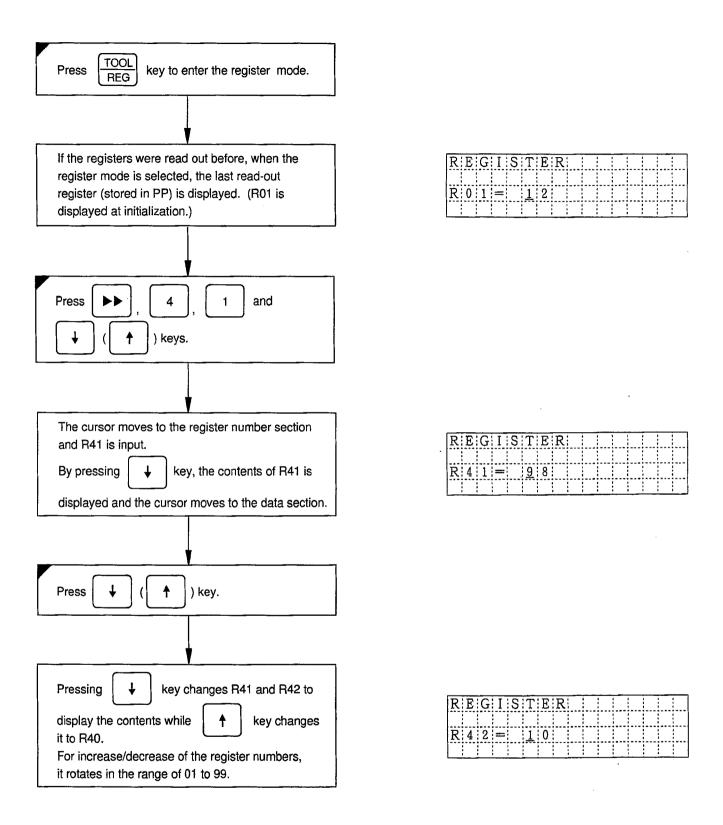
S	Р	Ι	Ν	D	L	E		Р	R	M		:			
							0	0	1	2	3	4	5	6	Η
	0	0	4	1	=		1	2	3	4	5	6	7	8	L
										;					

SPII	N D L	E: P	R:M:		
		0:0	1 1 2	2:3	3 H
0:0:	4 1 = 1	<u>4</u> 4	5 5 6	6:7	7 L

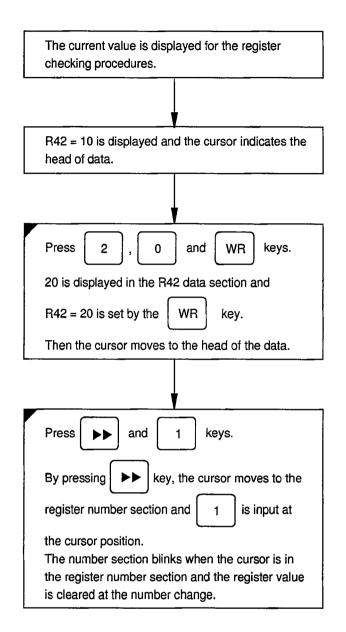
S	Р	Ι	N	D	L	Ε		P	R	M				:	
							0	0	1	1	2	2	3	3	Η
	0	0	4	1	=		4	4	5	5	6	6	7	7	L

S	P	I	N	D	L	Ε		Р	R	M			
			:				!						Η
	1	0	4	1	=								L
	-	:											

5.9 REGISTER CHECK



5.10 REGISTER CHANGE

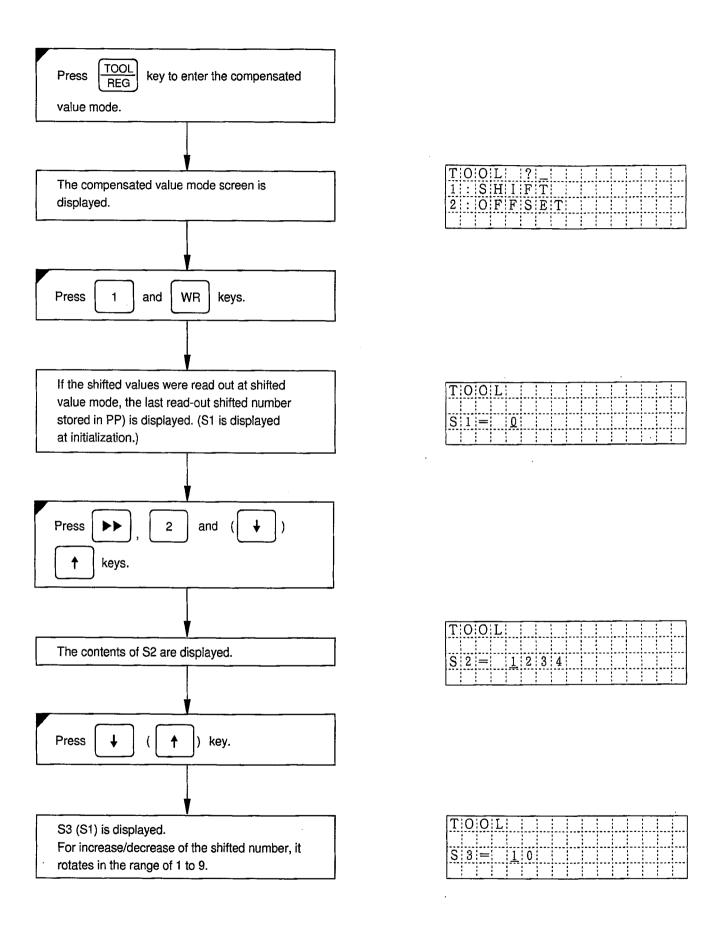


R: 4 2 = 1 0	REG	I S T	ER		
R:4 2 = <u>1</u> 0				 	
	R: 4 2	= 1	0	 	 ļļ -
			1 1		 <u> </u>

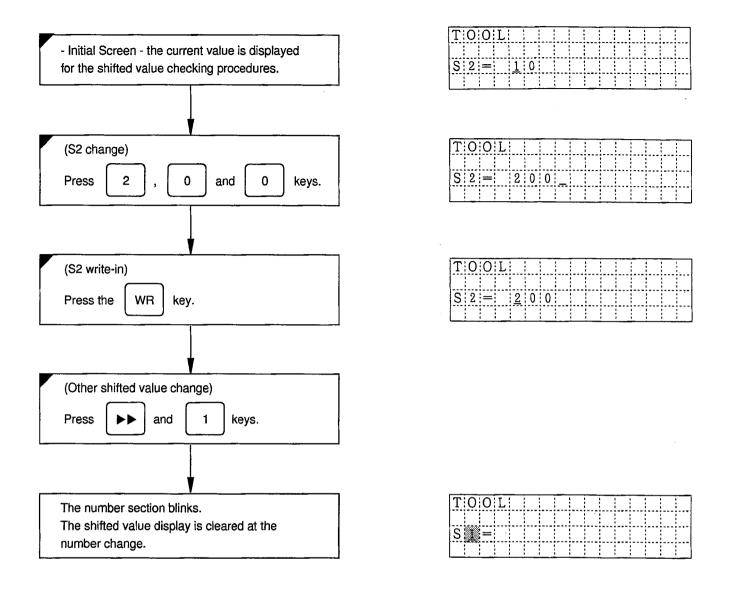
R	E	G	Ι	S	Τ	Ε	R				
R	4	2	=		<u>2</u>	0					

R E G	I S	TE	R		
R:1:2	=				

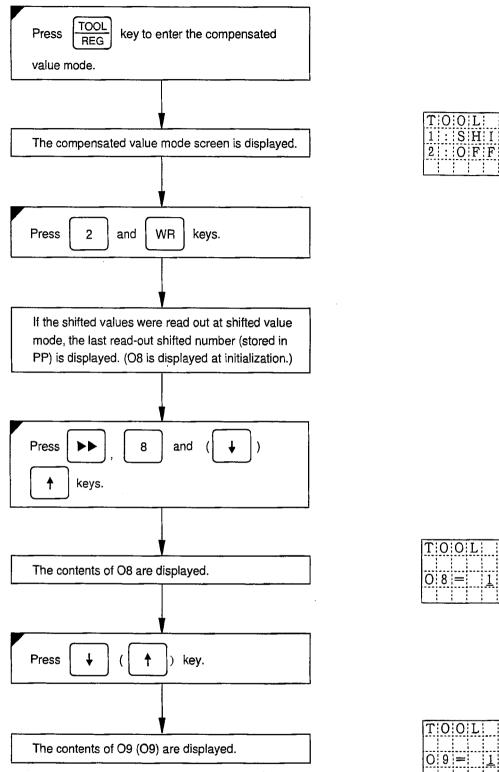
5.11 COMPENSATED VALUE (SHIFTED VALUE) CHECK



5.12 COMPENSATED VALUE (SHIFTED VALUE) CHANGE



5.13 COMPENSATED VALUE (OFFSET VALUE) CHECK



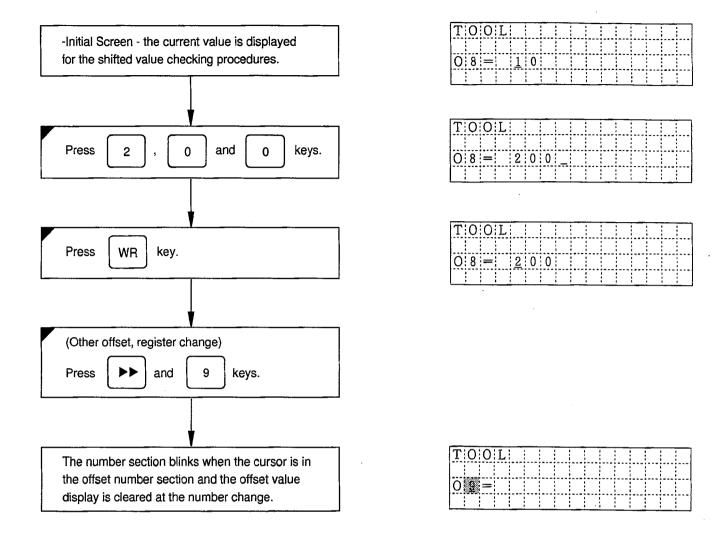
T:O	0	L		?				:			
1::	S	Η	Ι	F	Τ						
2 :	0	F	F	S	Ε	Т	 				

T	0	0	L									 		
0	8	=		1	2	3	4							
		•	•	• • • • •		•	•	•	:	:	:	 	:	

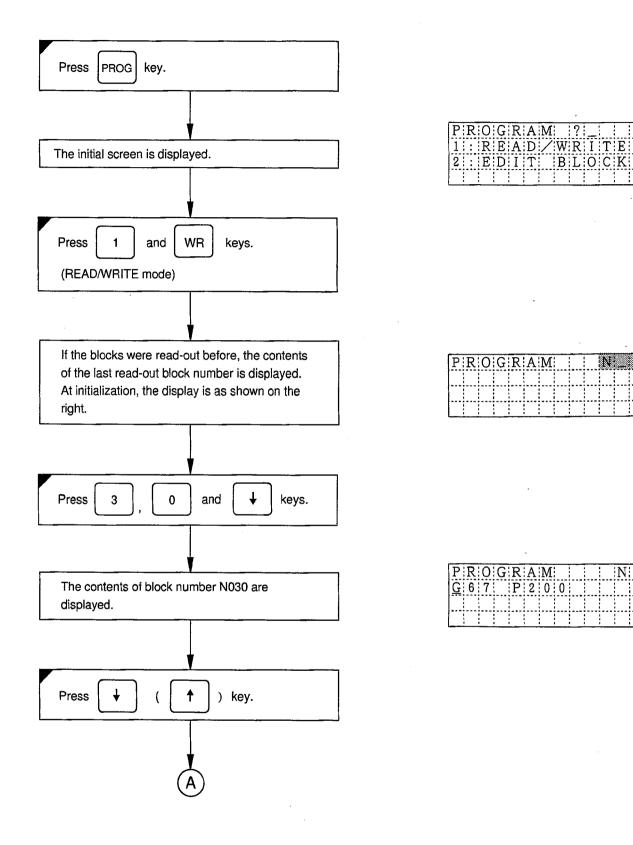
O 9 = 1 0	T 0 0) L					
O(9) = 1 0							
	O 9 =	1	0	.	ļļ	ļļ	<u> </u>

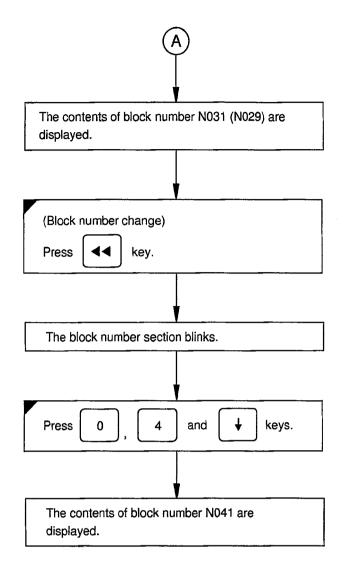
Only O8 and O9 are the offset values.

5.14 COMPENSATED VALUE (OFFSET VALUE) CHANGE



5.15 PROGRAM CHECK

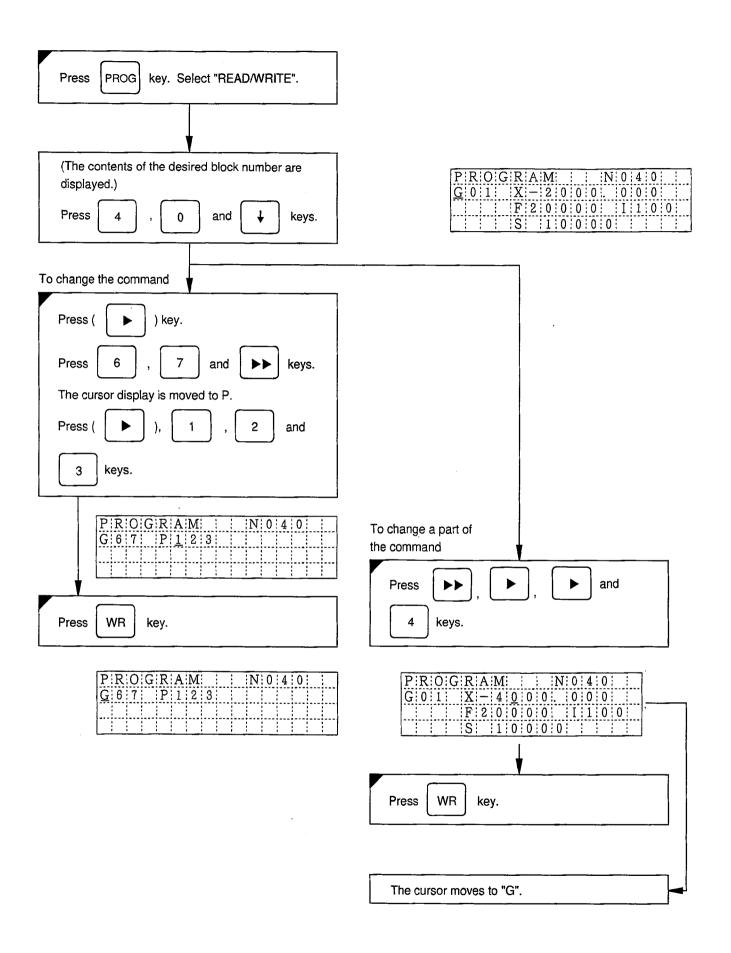




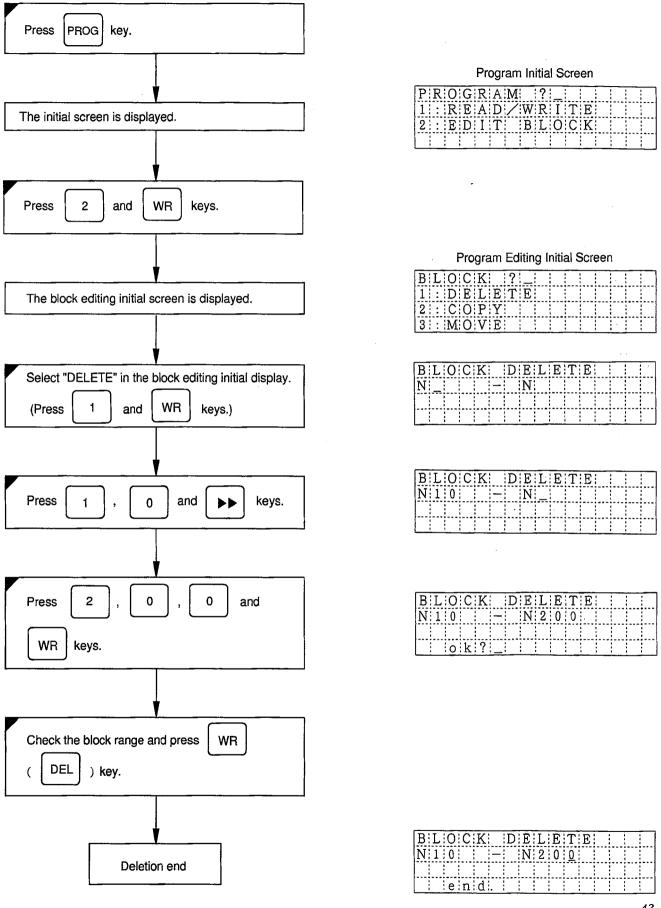
P:R:0) G	R A	M			:N	0	: 3	1	: :	
<u>G</u> 0:	1	X -	- 2	0	0	0 .	0	0	0	0	
		:F:2	2 : 0	0	0	0	Ι	1	0	0	
		S	1	0	0	0;0	-				

PR	OG	RA	M		<u>:N:</u>	3:3:1	
G: 0	1	X -	2 (0:0	0	0:0:0	0
		F: 2	0 (0 : 0	0 : :	I : 1 ; 0	0
		S	110	0:0	0 0		

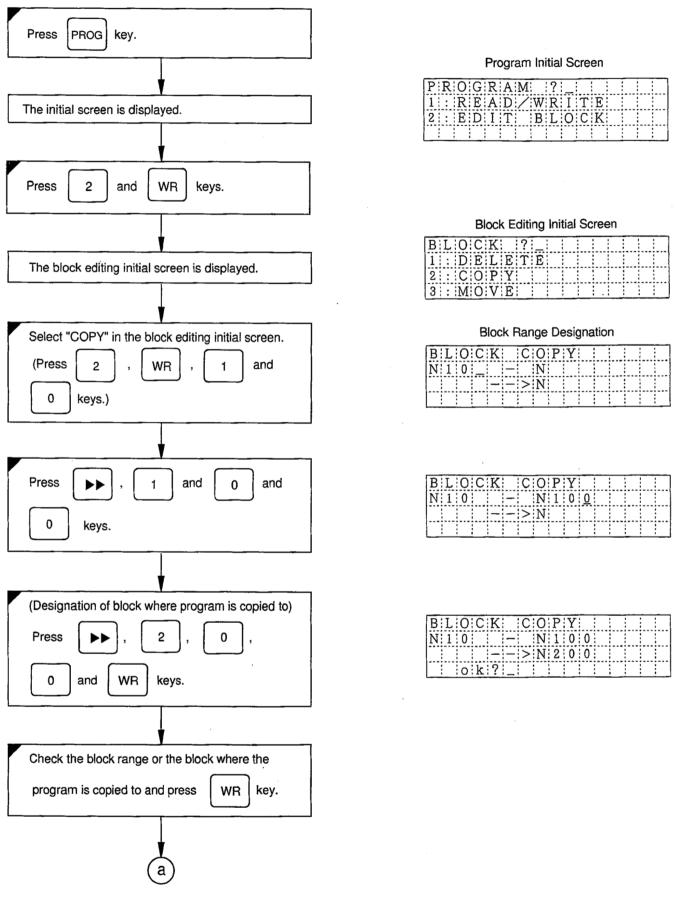
P:R:O	GRAM	N:0 4	1 1 1
<u>G</u> 0 5	X - 2 0	0:0:.:0:0	0:0:0:
	F 2 0 0	0:0: I	L O O
	S 10	0:0:0:	

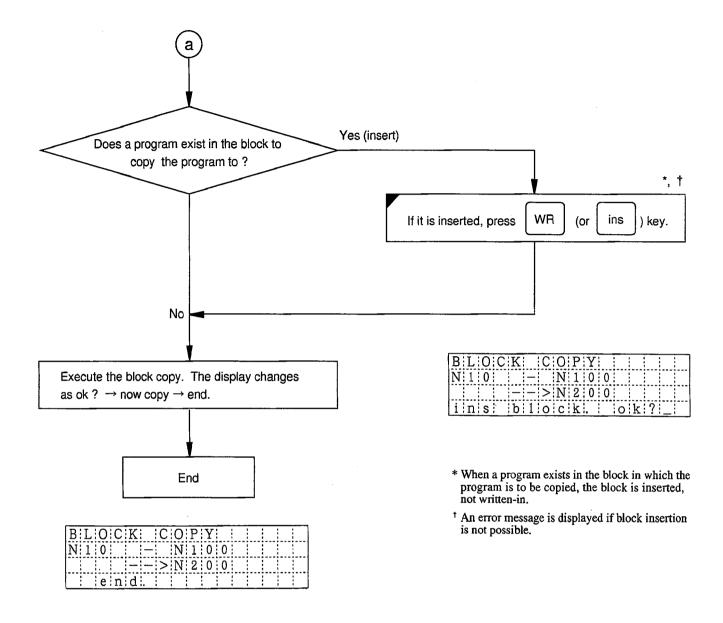


5.17 PROGRAM (BLOCK) DELETION

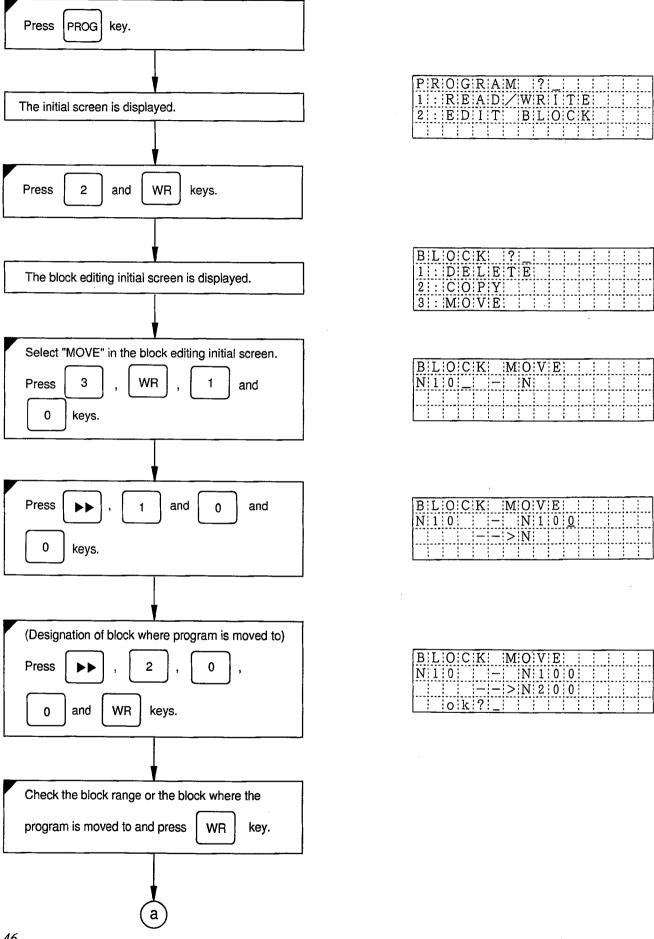


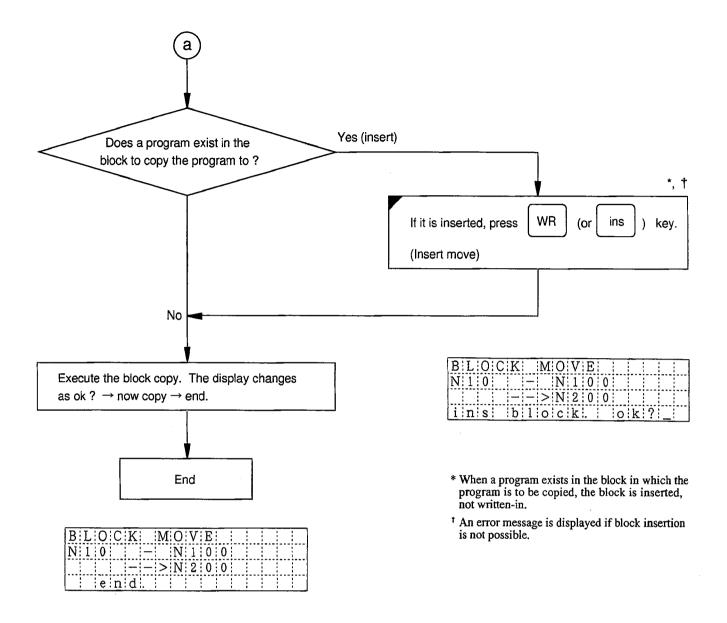
5.18 PROGRAM (BLOCK) COPY



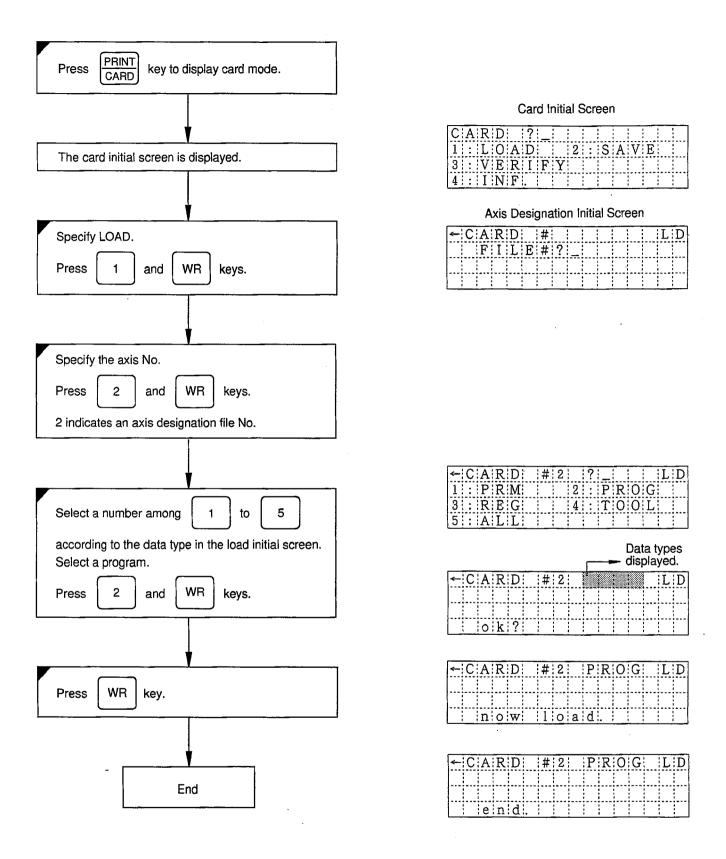


5.19 PROGRAM (BLOCK) MOVE

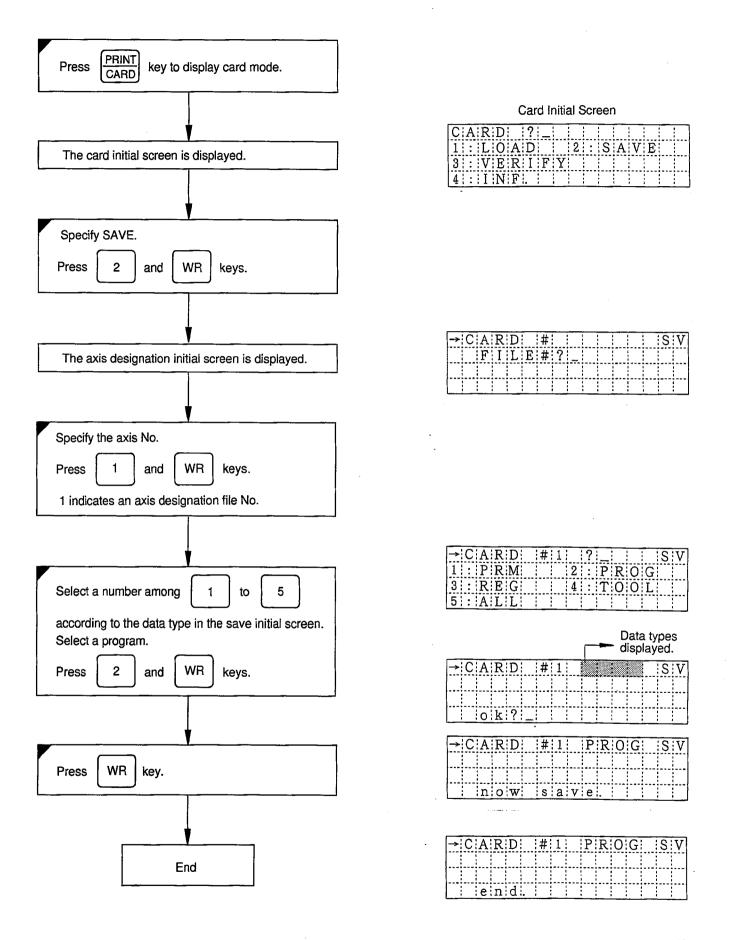




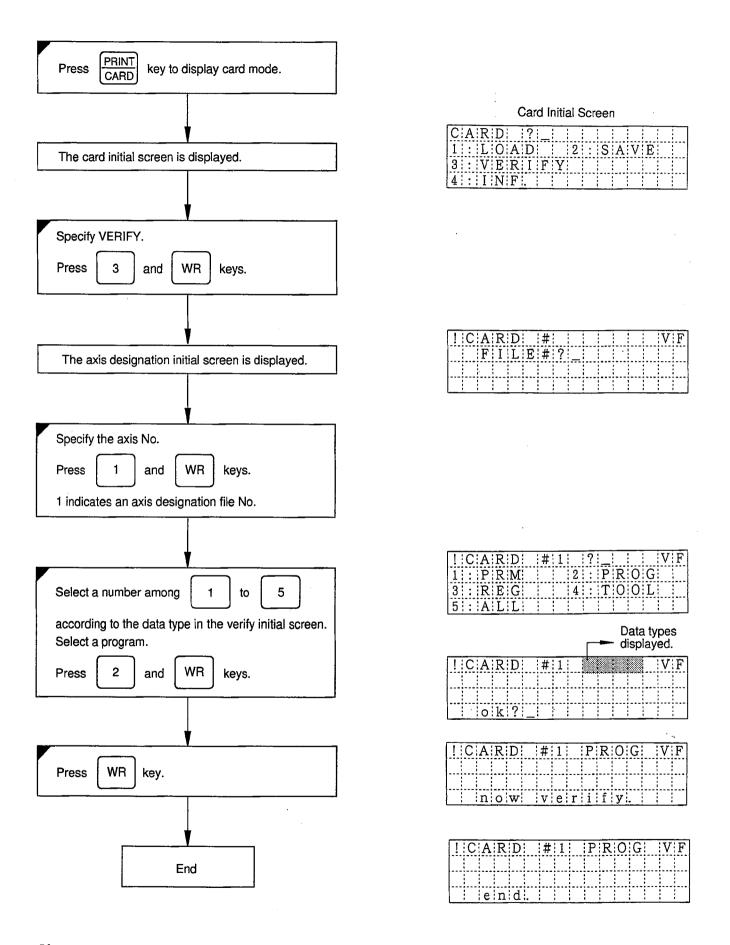
5.20 MEMORY CARD READ



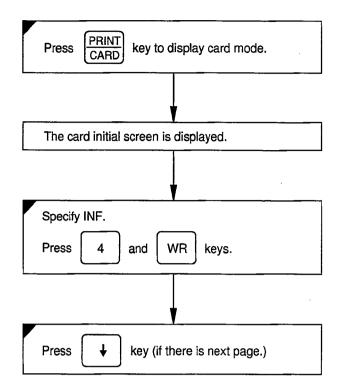
5.21 MEMORY CARD WRITE



5.22 MEMORY CARD VERIFY



5.23 MEMORY CARD DIRECTORY



Card Initial Screen

CARD	? _		
1:: L:O:A	D:	2:::S	A V E
3:: VER	I F Y		
4: I N F			

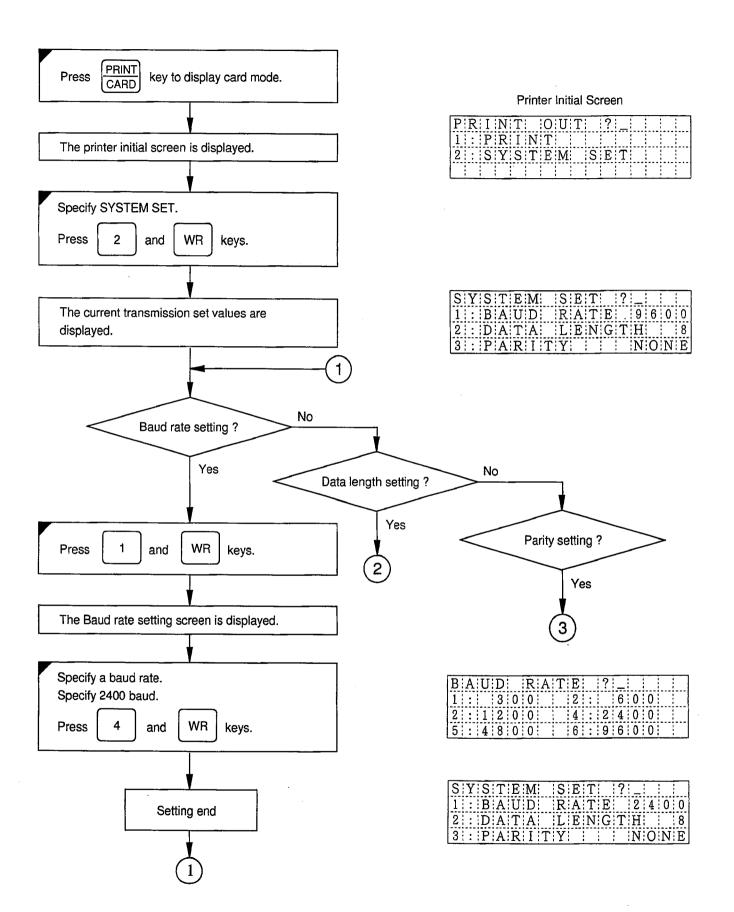
Directory Display Screen

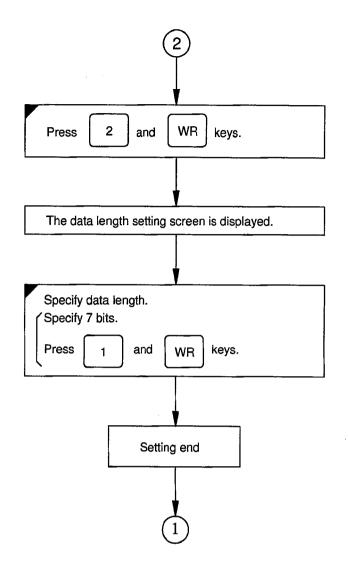
CARD:	INF.	F:#:1:-:#:4
F:#:1:(P	r, Pg,	Rigi, T:1:)
F:#:2:(P	ri,	Rg, T1)
F:#:3: (:P	r, Pg,	T:1:)

C	Α	R	D		Ι	Ν	F			F	#	1	_	#	4
F	#	4	(Р	r	<u>.</u>	Р	g	,				Т	1)
						<u> </u>	<u>.</u>	<u>.</u>	!						
				:		:	:	:	:	:					

5.24 PRINT-OUT

5.24.1 Transmission Conditions Setting

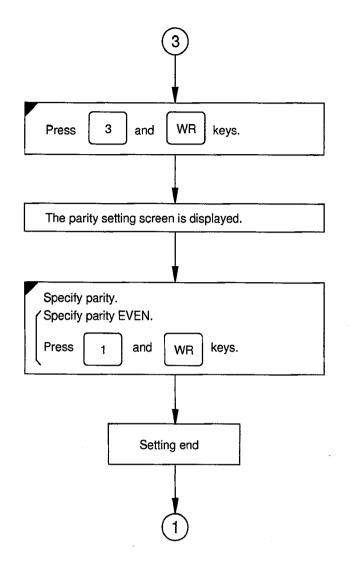




D	Α	Τ	A		L	Ε	N	G	Τ	Η	?	_	
1	:	7	b	i	t								
2	:	8	b	i	t								
								:					

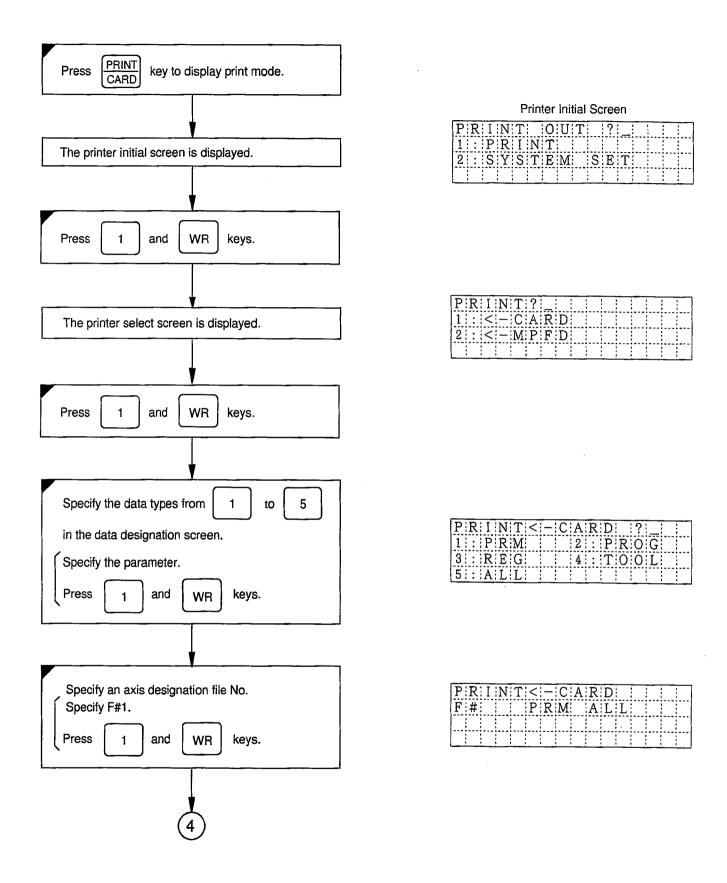
S:Y:S:T:E:M:	:S:E:T: :	?:_::::
1:: B:A:U:D:	RATE	9 6 0 0
2::DATA	LENG	T:H: : 7
3:::PA:R:I:7	Γ:Y: : :	NONE

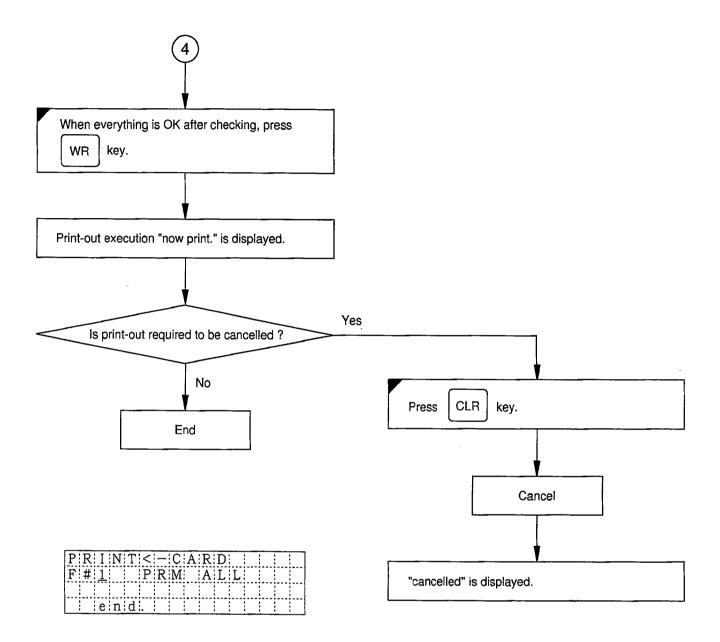
5.24.1 Transmission Conditions Setting (Cont'd)



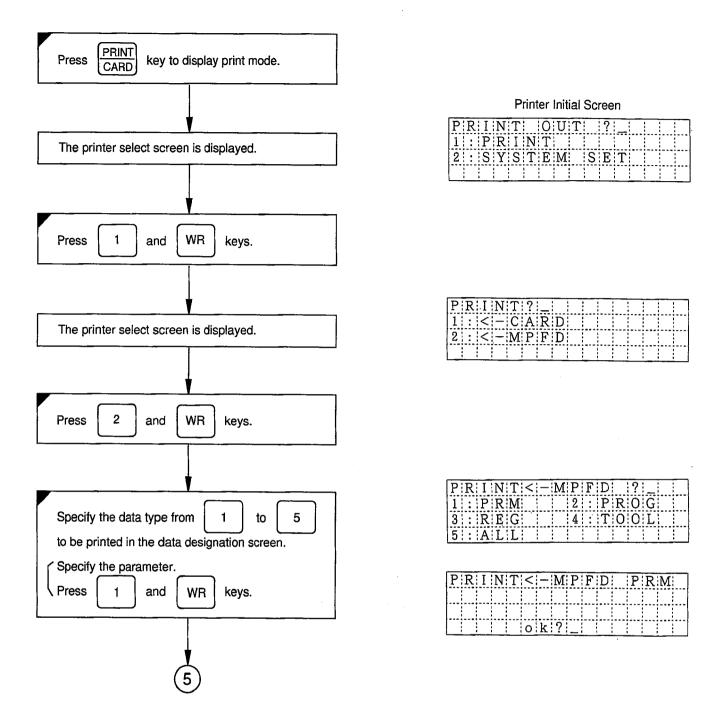
P:A:R:I:T:Y:	?	-	:			
1:: E:V:E:N:						
2::ODD			;			
3:::N:O:N:E:		:	;			

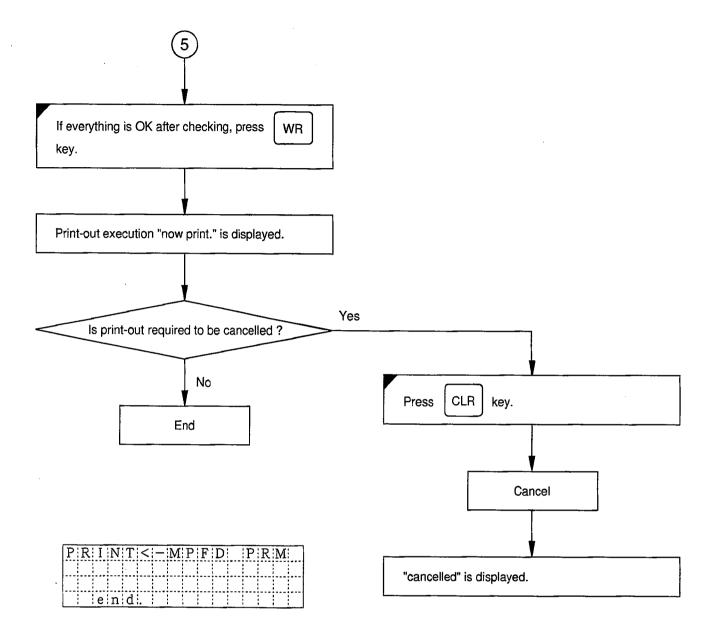
SYSTEM	SET ?_
1:: B:A:U:D	RATE: 9:6:0:0
2::DATA	LENGTH: 8
3:: PARI	r y EVEN

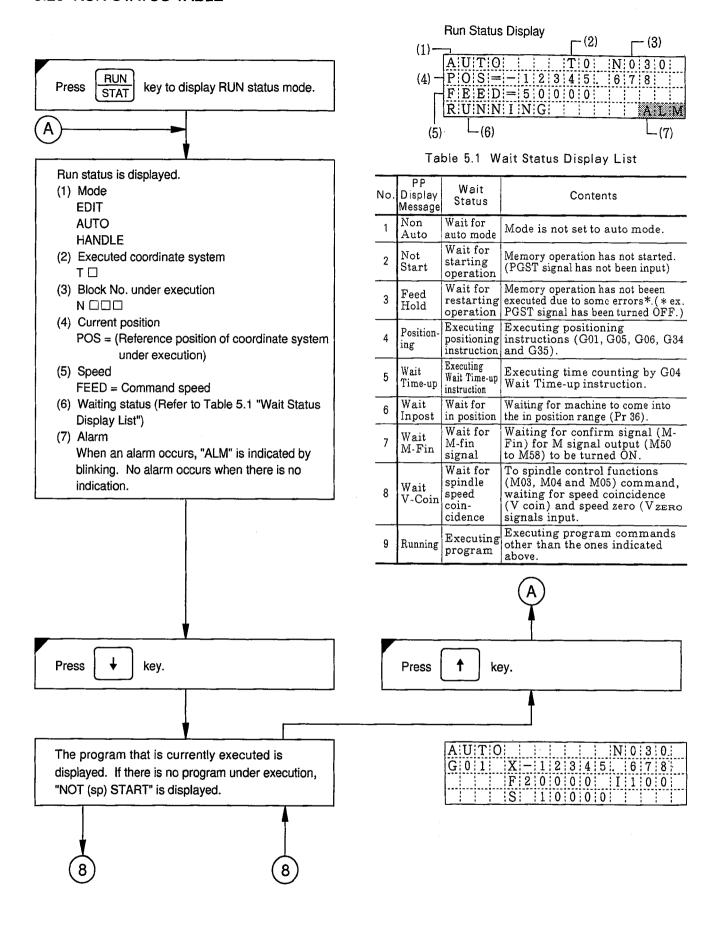


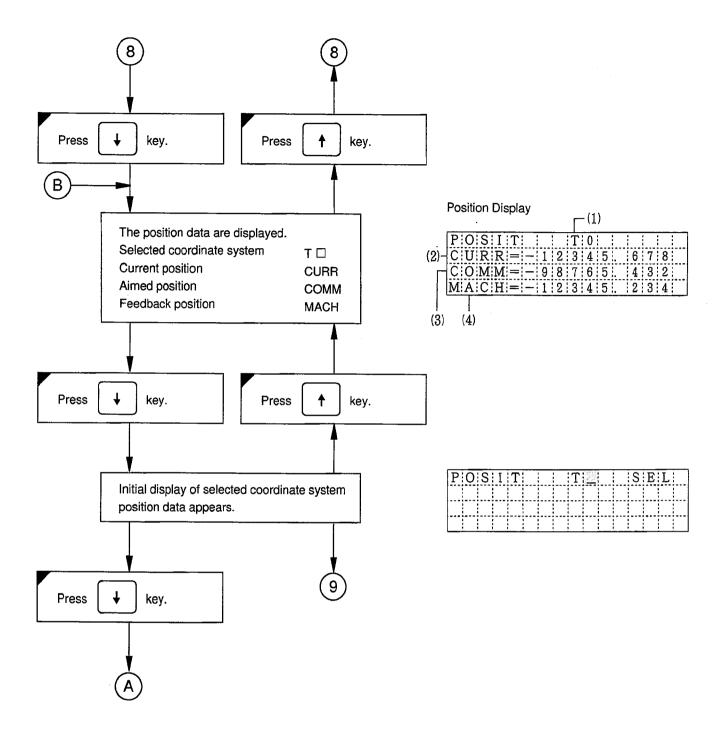


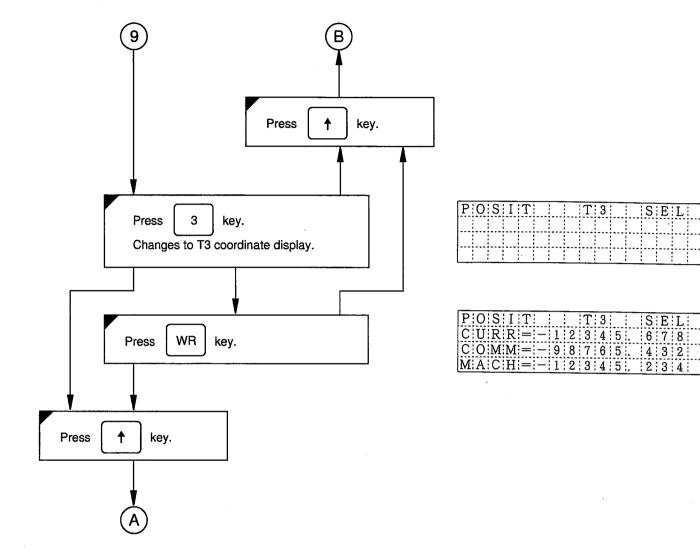
5.24.3 Motionpack Contents Print-out



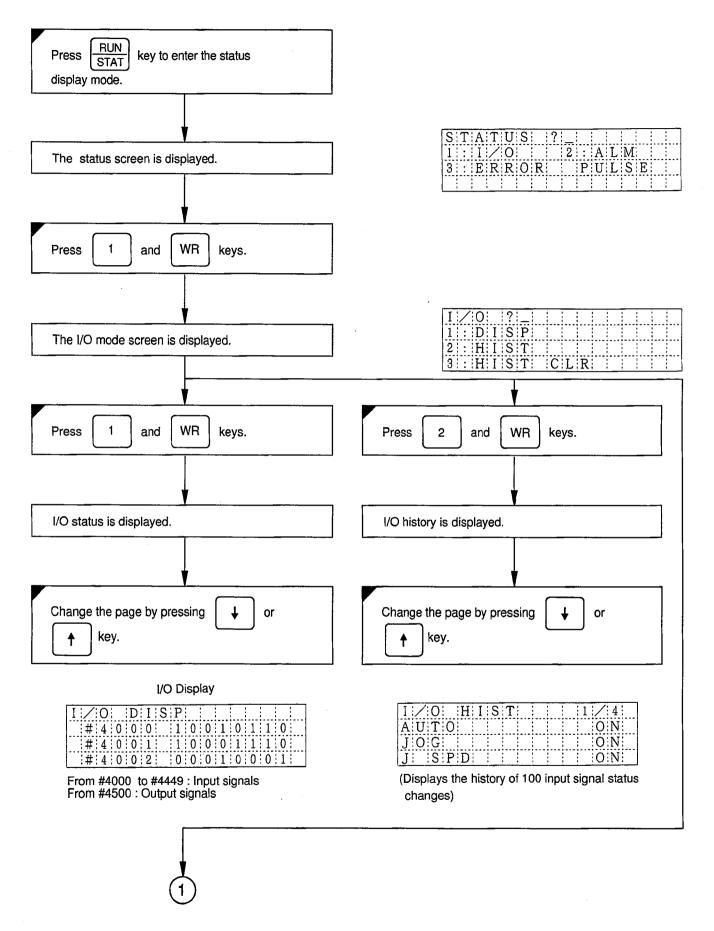


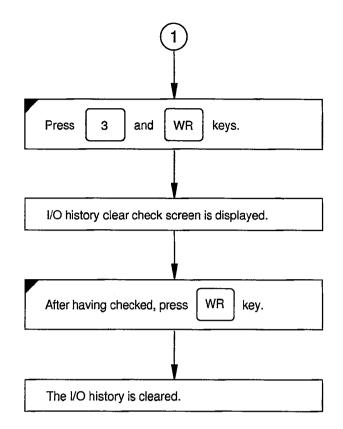






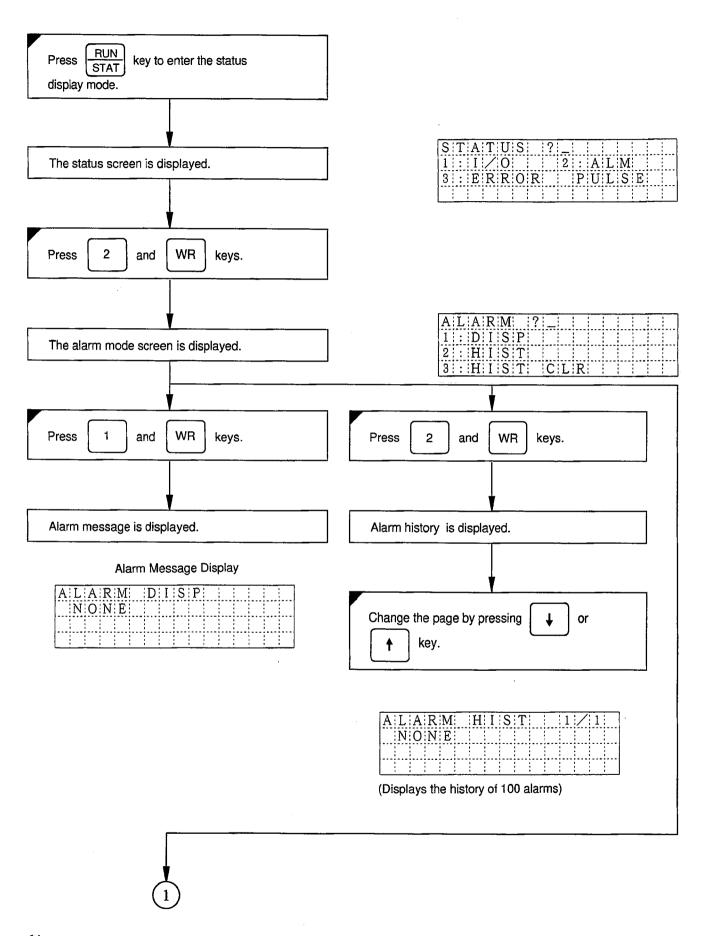
5.26 STATUS SCREEN (I/O STATUS, I/O HISTORY, I/O HISTORY CLEAR)

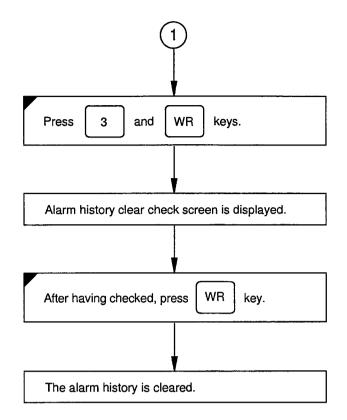




Ī	/	0		Н	Ι	S	Τ	;	С	L	R				
		Y	е	s	:	W	R	/	Ν	0	:	C	L	R	
					0	k	?	_							

Į	I	/	0		Η	Ι	S	Т	С	L	R			
			е	n	d							 	:	:

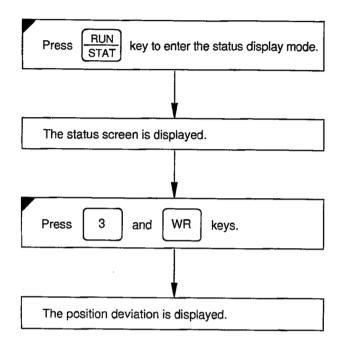


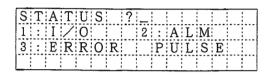


A	L	Α	R	M		Η	Ι	S	Τ		С	L	R		
l															
l		Y	е	s	:	W	R	/	Ν	0	:	С	L	R	
						0	k	?	_						

AL	AR	M	H: I	ST	CL	R
1						
					: :	
	e n	d.				

5.28 STATUS DISPLAY (ERROR PULSE)

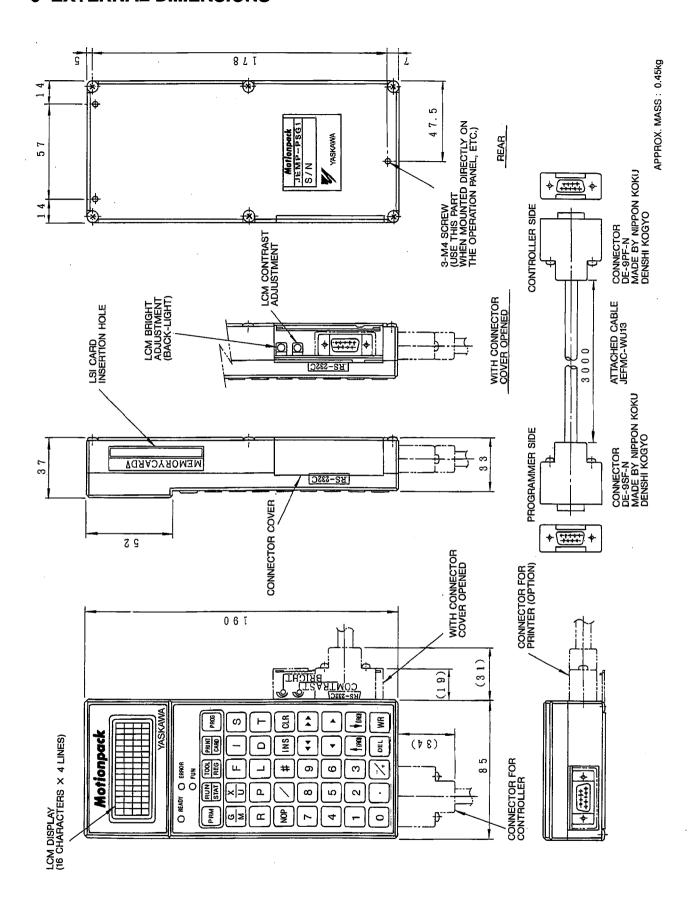




Position Deviation Display

E	R	R	0	R		Р	U	L	S	Ε					
R	U	L	S	Ε	=	1	2	3	4	5		6	7	8	
															<u>.</u>
						:	:		:		:		;		:

6 EXTERNAL DIMENSIONS



MOTIONPACK-SG1

DESCRIPTIVE INFORMATION

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