

**MODBUS vs MEMOBUS (revised)**  
**Yaskawa System Applications Engineering Group**

This document describes the difference between Memobus and Modbus. For additional detailed information please refer to the following documents:

- SIE-C815-13.60E “Memobus Descriptive Information”
- SIEZ-C887-1.2 “Machine Controller MP9\*\* Ladder Programming Users Manual”

When communicating with an MP9\*\* series controller and an HMI, the HMI should be the master, and the MP9\*\* should be the slave. Up to 63 slaves can be addressed using Memobus. The DEFAULT HMI Driver protocol settings are as follows:

- Transmission rate: 9600 baud
- Transmission mode: RTU (Remote Terminal Unit)
- Data: 8 bits
- Parity Check: Even parity
- Stop bit: 1 bit
- Error Check: CRC-16 (Cyclic Redundancy Check)
- Transmission: Half duplex, asynchronous
- MP9\*\* Port: port #2
- Slave Address: 1

The MP9\*\* controller will use a message receive function called “MSG-RCV”, in slave mode. This function accepts standard Modbus function codes in its messaging format. The HMI Driver should support the following function codes for the MP9\*\* series controllers:

Function Code	Register	Description	Max QTY per Query message
01H	MBXXXXXX	Read Bit Condition	2000
02H	IBXXXXX	Read Physical Hardware Input	2000
03H	MWXXXXX	Read Contents of Holding Register	125
04H	IWXXXXX	Read Contents of Physical Hardware Input Word	125
05H	MBXXXXXX	Write to Single Bit	1
06H	MWXXXXX	Write to Single Holding Register	1
08H	-	Loop-back test	-
09H	MWXXXXX	Read Contents of Holding Register (expanded)	252
0AH	IBXXXXX	Read Physical Hardware Input (expanded)	252
0BH	MWXXXXX	Write to Multiple Holding Register (expanded)	251
0DH	MWXXXXX	Discontinuous read of holding register (expanded)	
0EH	MWXXXXX	Discontinuous write of holding register (expanded)	
0FH	MBXXXXXX	Change conditions of multiple bits (expanded)	
10H	MWXXXXX	Write to Multiple Holding Register	100

Note that physical hardware outputs are not supported by the Memobus protocol, the reason for this is for safety and to avoid conflicts due to un-planned writing of direct control outputs between the HMI and MP9\*\* ladder program.

Memobus essentially uses the Modbus protocol, however, the difference lies in how the MP series controllers interprets the registers. HMI Memobus Drivers should be written with the following considerations:



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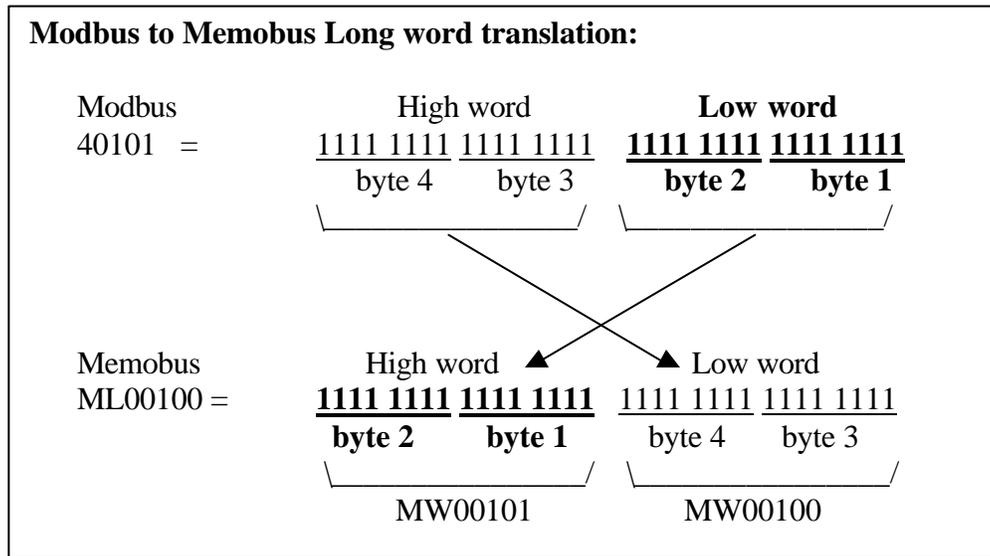
- 6) Long words consist of 32 bits (two words), high and low words are to be swapped. Address is expressed in decimal.

address range: ML00000 to ML32766, value range: -2147483648 to +2147483647

Example for MP930:

ML00100 consists of MW00100 (low word) and MW00101 (high word)

See chart below:



- 7) Floating point words are 32 bits and are in INTEL 486 Single precision format (IEEE Floating Point). Address is expressed in decimal.  
 address range: MF00000 to MF32766, value range: +/- (1.175E-38 to 3.402E+38),0 Intel 486 single precision format. Bit 31=sign, bit 23-30 is biased exponent, bit 0-22 is significant.  
 All MP Series products round to display real numbers (floating point) to display 7 digits (if the 8<sup>th</sup> digit is 5 or greater, then the 7 digit is rounded up).
- 8) Input registers are accessible for direct monitoring at the HMI. IB, IW, IF. Address is expressed in hex.  
 address range (MP940): IW0000 to IW07FF (2048 decimal)  
 \*address range (MP930): IW0000 to IW0FFF (4096 decimal)  
 Please only use the (\*) for max value.
- 9) Output registers (physical output points) are not accessible in memobus.
- 10) Field entries in HMI should be auto-configurable when the data type is detected after user entry.

Data type	Default # digits	Default Display
Bit	1	Bit
Word	6	Signed 16-Bit
Long word	11	Signed 32-Bit
Floating point word (real)	11	Floating point with Exponent